#### Zürcher Hochschule für Angewandte Wissenschaften

# **Deep Learning für Dokumentenanalyse**

*Kolloquium der ETH Bibliothek, online, 25. März 2021* Thilo Stadelmann





zhaw.ch/datalab



# **Document analysis?**



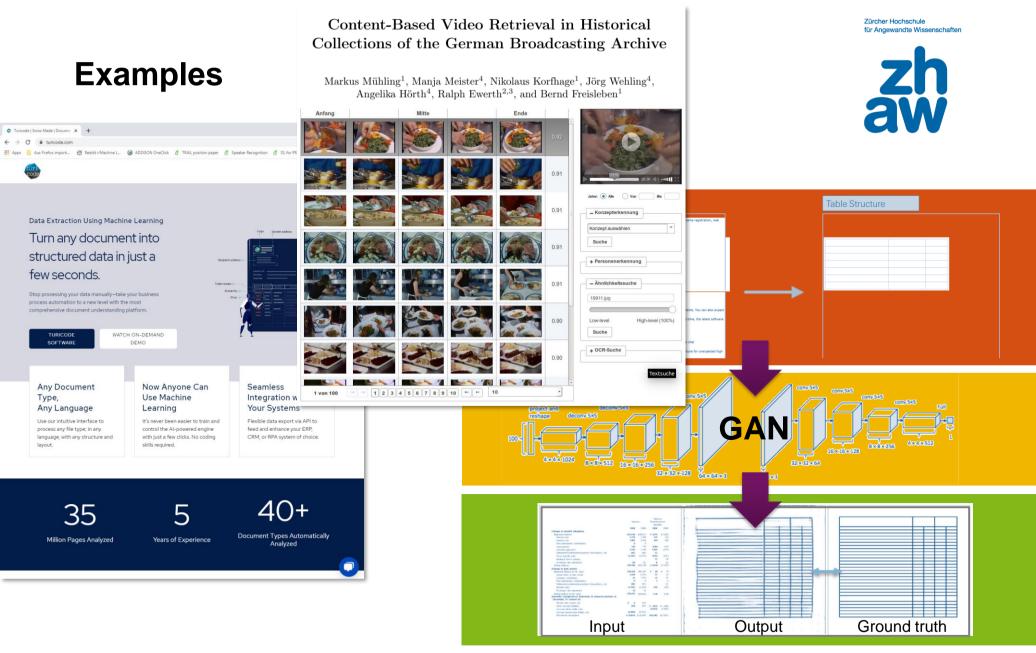
### Documents

- Ubiquitous in human communication and every scenario involving an office
- Somewhat structured for human expert; unstructured w.r.t machines
- Great use case for various AI techniques, including computer vision

### Own scientific community

• IAPR's biannual Intl. Conference on Document Analysis & Recognition (ICDAR): character & symbol recognition, printed/handwritten text recognition, graphics analysis & recognition, document analysis & understanding, historical documents & digital libraries, document-based forensics, camera & video-based scene text analysis

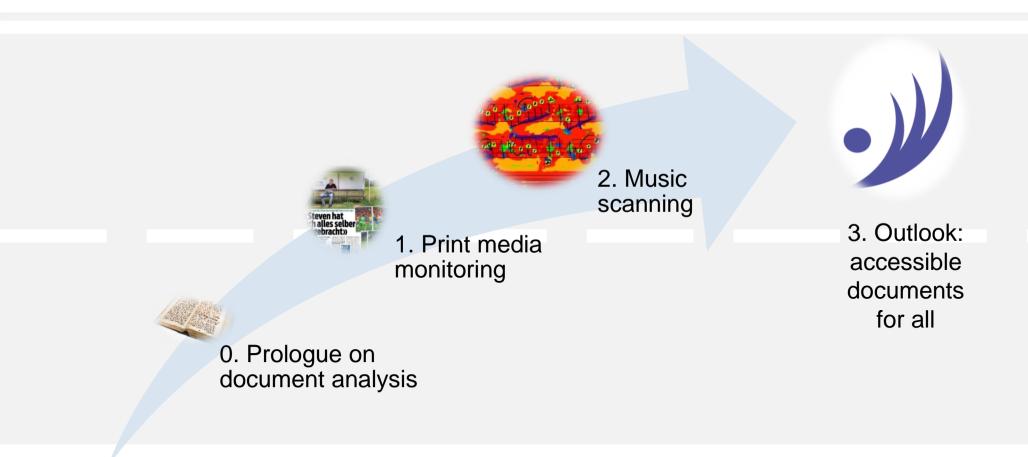




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# Roadmap





# 1. Print media monitoring



### Task



### Challenge



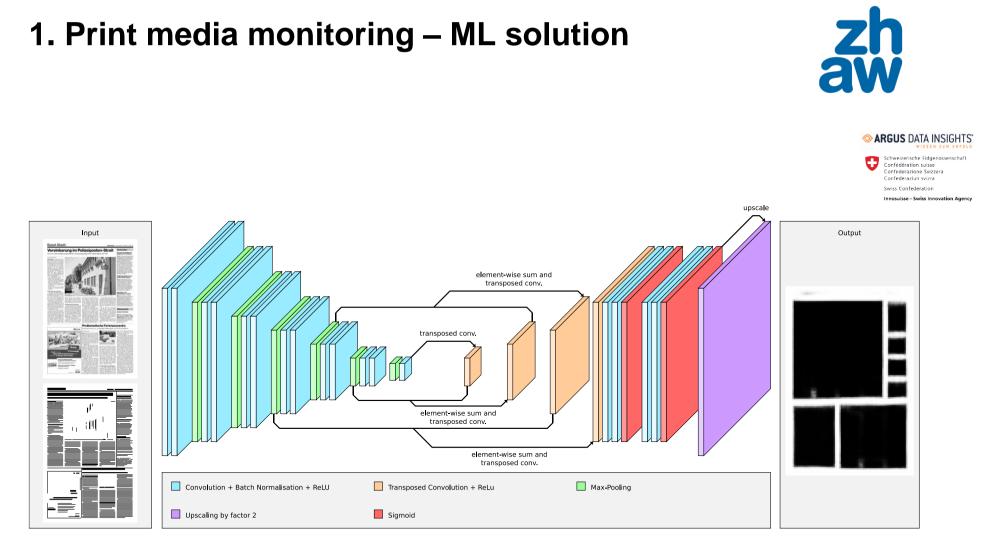
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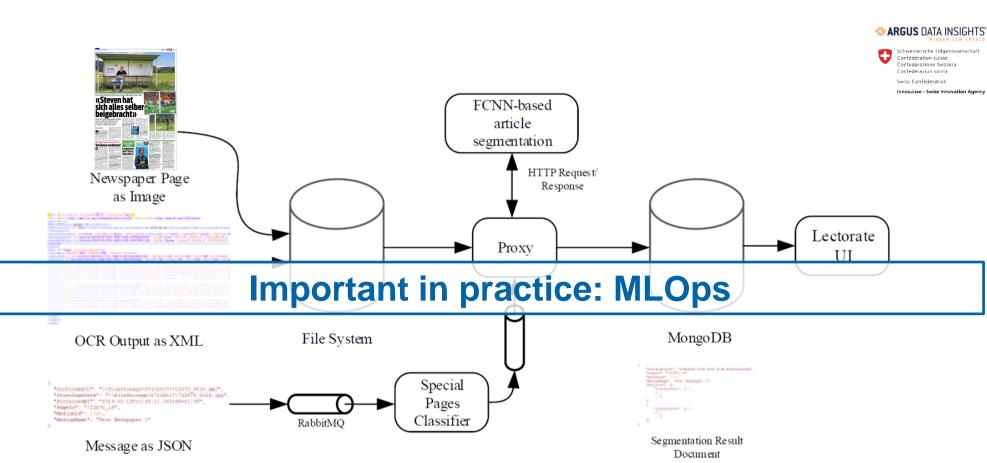
Innosuisse – Swiss Innovation Agency





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# 1. Print media monitoring – deployment



Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

# 2. Music scanning

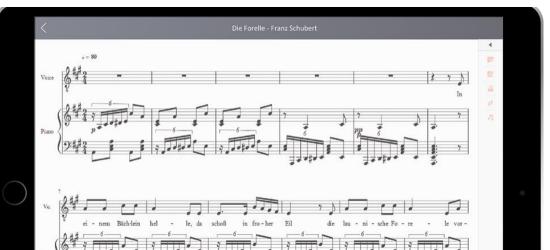
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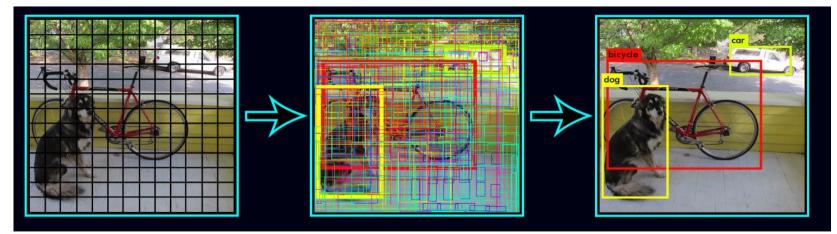
## 2. Music scanning – challenges & results Score Pad (a) (b) kevSharp accidentalSharp Schweizerische Fidnenos Confédération suisse Confederazione Suizzar: Confederaziun svizra Swiss Confederation Innosuisse - Swiss Innovation Agend (c)(d)augmentationDot articStaccatoAbove a) Example result from *DeepScores* with detected bounding boxes as overlays. The tiny numbers are class labels from the dataset introduced with the overlay. This system is roughly one forth of the size of a typical DeepScores input we process at once.

**b**) Example result from *MUSCIMA*++ with detected bounding boxes and class labels as overlays. This system is roughly one half of the size of a typical processed *MUSCIMA*++ input. The images are random picks amongst inputs with many symbols.

Tuggener, Elezi, Schmidhuber, Pelillo & Stadelmann (2018). «DeepScores – A Dataset for Segmentation, Detection and Classification of Tiny Objects». ICPR'2018. Tuggener, Satyawan, Pacha, Schmidhuber & Stadelmann (2020). «The DeepScoresV2 Dataset and Benchmark for Music Object Detection». ICPR'2020. Tuggener, Elezi, Schmidhuber & Stadelmann (2018). «Deep Watershed Detector for Music Object Recognition». ISMIR'2018.

## Music scanning – methodology (differentiation) OMR vs state of the art object detectors

### YOLO/SSD-type detectors



Source: https://pjreddie.com/darknet/yolov2/ (11.09.2018)

### **R-CNN**

- Two-step proposal and refinement scheme
- Very large number of proposals at high resolution needed

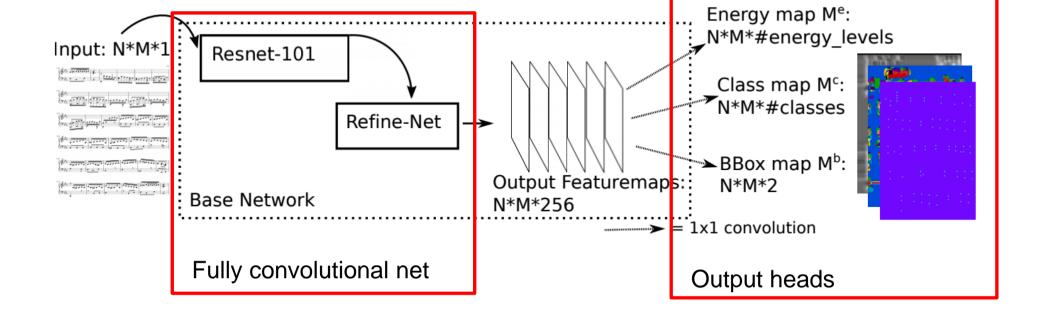




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## 2. Music scanning – methodology (ours) The deep watershed detector

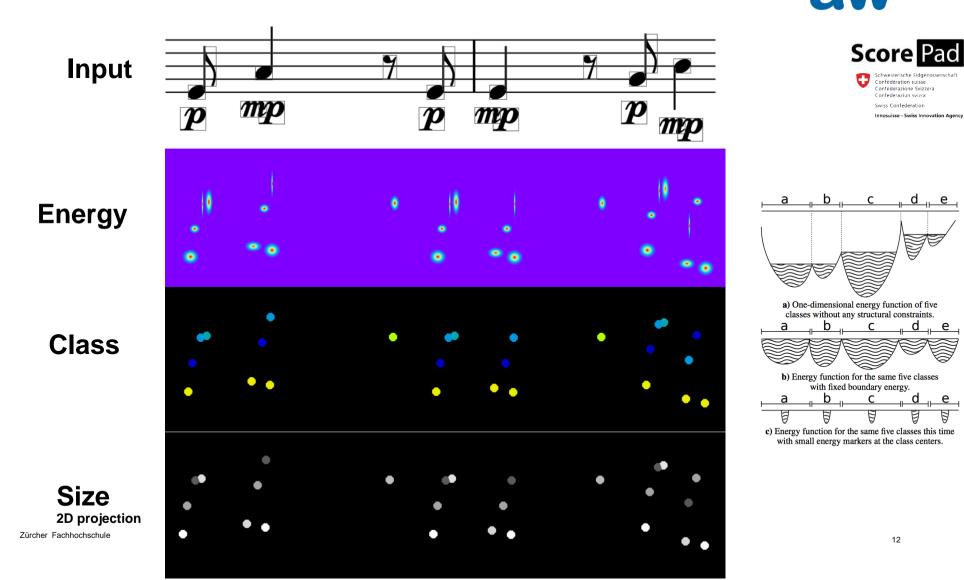




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## 2. Music scanning – methodology (details) Output heads of the deep watershed detector

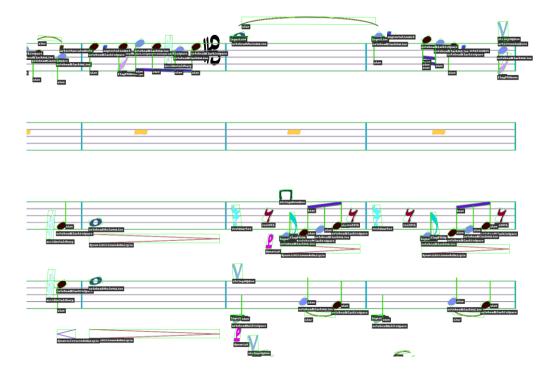


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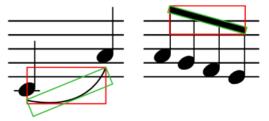
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## 2. Music scanning – recent work

1. Extension of the detection alphabet to 135 classes (updated dataset released)



2. Natural incorporation of rotation







Model training

## **2. Music scanning – future work** Dealing with real world noise

# Synthetic quality + labels: perfect quality





**Data distribution shift** 

Real world quality: print/scan artifacts, wrinkles, dirt, ...

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Remedy:

Use semi-supervised learning to model distribution change and/or disentangle latent signals

Model deployment

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# 3. Outlook – lessons learned



Data is key

- Many real-world projects miss the required quantity & quality of data
   → even though «big data» is not needed
- Class imbalance needs careful dealing
   → special loss, resampling (also in unorthodox ways)
- Unsupervised methods need to be used creatively
- Users & label providers need to be trained

Prerequisite: stable data & label acquisition pipeline

Learning from (raw) data is powerful, yet one is fully dependent on what is in that data

Robustness is important

- Training processes can be tricky
  - $\rightarrow$  give hints via a unique loss, proper preprocessing and pretraining

Sufficient condition: lots of tuning

# 3. Outlook – accessible documents for all

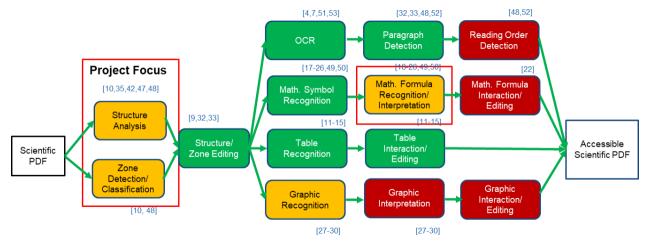


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The document will be read out loud in the reading order stated below. You can change the reading order per drag and drop. As soon as you are finished, go back to the tab TASKS.	Proof. 1 4We have $q_i \delta_j = p \delta_0$ by the corollary to Proposition 5. Therefore, it is sufficient to prove (2) for $k \ge 2$ . Set $\sigma = i_k$ , and let us consider the surface $M_{\sigma}$ obtained by the $(\sigma - 1)$ —th blowing up in the process to get $M$ from $M_j$ . We may say that $M_{\phi}$ is the surface obtained by the blowing down of $L_{h+1}$ , $L_{h+1}$ ,, $L_{h+1}$ successively from $M$ . Let $\pi_{\phi}$ : $M \rightarrow M_{\phi}$ be the		
□ All ▼	contraction mapping. As in the previous sections, let us denote the proper images of $\overline{C}$ , $\overline{C}_k$ , $E_i$ in $M_\sigma$ by $\overline{C}^{(\sigma)}$ , $\overline{C}^{(\sigma)}_k$ , $E_i^{(\sigma)}$ respectively. By Theorem 3,		
Paragraph Page 1 2 T	$\overline{C}_{k+1}^{(d)}$ intersects transversely $E_{\sigma}^{(d)}$ at the same point $Q = \pi_{\sigma}(L_{k+1} \cup \cdots \cup L_{k+1})$ $as \overline{c}^{(d)}$ . Hence, the functions $f$ and $g_{k+1}$ on $M_{\sigma}$ have the same indetermination point $Q \in E_{\sigma}^{(d)}$ . Let $P_{R}^{(d)} = P_{R}^{(d)} + P_{R}^{(d)} +$		
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Page 1 r agraph (o)	$\overline{\delta}_0 = p_{\mu\nu}\overline{\delta}_1 = p_{\mu\nu}\cdots \overline{\delta}_n = p_{\mu\nu}$ . The coefficients $\nu_i, \nu_i(i = 0, 1, \cdots, \sigma)$ are the solutions of the following equations:		
Paragraph Page 1 pointQ E E . Let	$\sum_{j=0}^{\sigma} (E_i^{(\sigma)} \cdot E_j^{(\sigma)})\nu_j = \begin{cases} 0(i \neq \sigma) \\ d_{k+1}(i = \sigma), \\ \sum_{\sigma=0}^{\sigma} (E_i^{(\sigma)} \cdot E_j^{(\sigma)})v_j = \begin{cases} 0(i \neq \sigma) \\ 1(i = \sigma). \end{cases}$		
□ Page 1 Page 1 oXoX(o)(o)(o)(o)P=vE,P=vEfii9k+1ii	Hence, by Lemma 4, we have $\nu_{\epsilon} = d_{k+1}\overline{\nu}_{\epsilon}$ for all $i = 0, 1, \cdots, \sigma$ . In particular, $\delta_i = \overline{\delta}_i \cdot d_{k+1}, \ (i = 0, 1, \cdots, k).$		
Paragraph Page 1 Page 1	Therefore, in order to prove (2), it is sufficient to prove (3) $q_k \vec{\delta}_k \in \mathbb{N} \vec{\delta}_0 + \mathbb{N} \vec{\delta}_1 + \cdots + \mathbb{N} \vec{\delta}_{k-1}$ . By Theorem 3, $\overline{C}_k^{(\sigma)}$ intersects $E_{4s}^{(\sigma)}$ transversely and does not inter- sects		
□	by incorem 3, $C_k$ intersects $E_{j_k}^{(s)}$ transversely and does not inter- sects other components $E_i^{(s)}(i \neq j_k)$ . We have $\overline{\delta}_k = (P_{g_{k+1}}^{(s)}, \overline{C}_k^{(s)})$		
Paragraph Page 1 Page 1	$= (\overline{C}_{k+1}^{(\sigma)} \cdot \overline{C}_{k}^{(\sigma)}) \\= (\overline{C}_{k+1}^{(\sigma)} \cdot P_{gk}^{(\sigma)}).$		
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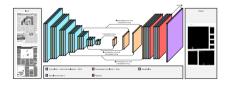
# 3. Outlook – research approach

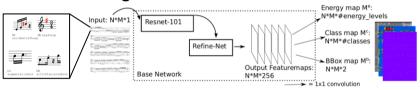


- Goal is a semi-automatic process to make scientific documents accessible
- Focus on structure analysis & mathematical formula recognition



Build on previous experience & methods for newspapers and OMR structure recognition formula recognition





Contact

Martin Braschler · Thilo Stadelmann

Kurt Stockinger Editors

Applied

Science

Lessons Learned for the Data-Driven Business

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Data

Braschler - Stade Stockinger Eds.

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Applied Data Science

- Document analysis is a **very fruitful use case** for Deep Learning (for archives + R&D)
- Latest research is applied and deployed in «normal» organizations (e.g., libraries)
- It does not need big-, but some data (effort usually underestimated)
- DL/RL training for new use cases can be tricky (→ needs experience)

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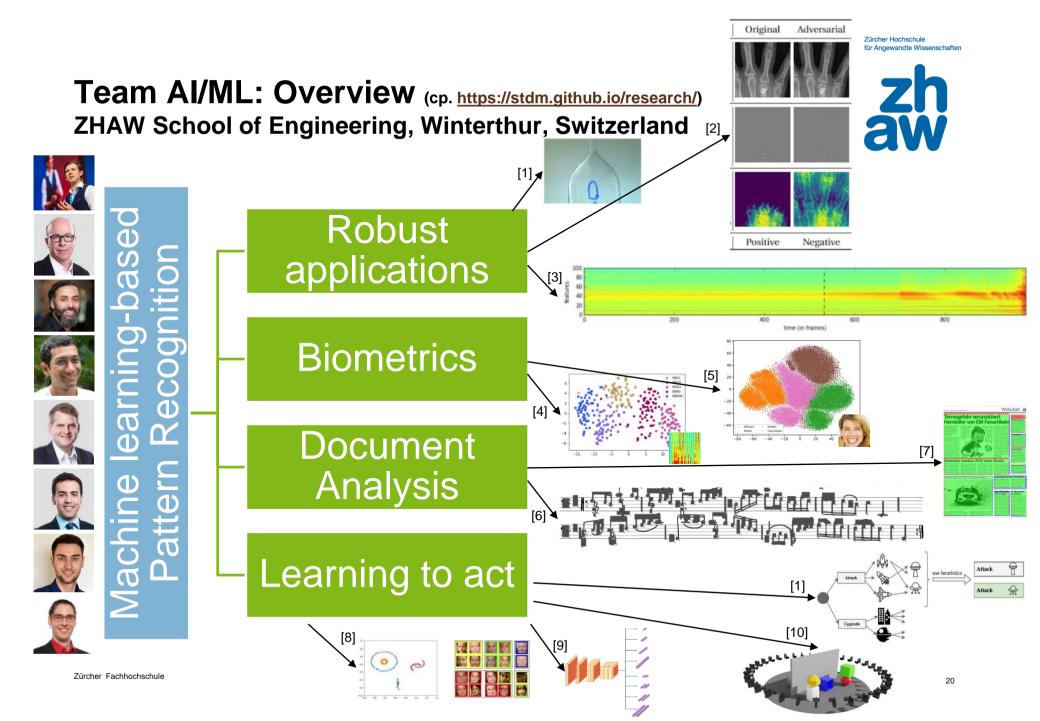


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## **APPENDIX**



## **References for overview**

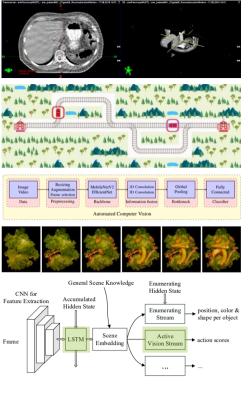


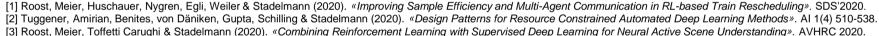
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# Outlook: Late-breaking results

- · · · · · · · · · · · · · · ·
- Medical image analysis: learning to reduce motion artifacts in 3D CT scans
- Learning an artificial communication language for multi-agent reinforcement learning in logistics (notable rank in Flatland 2019 competition, best poster award [1])
- Automated deep learning (top rank in AutoDL 2020 challenge [2])
- Learning to segment and classify food waste in professional kitchens under adversarial conditions [4]
- Improving robotic vision through active vision and combined supervised and reinforcement learning (Dr. Waldemar Jucker Award 2020 [3])

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[4] Simmler, Sager, Andermatrit, Chavarriaga ,Schilling, Rosenthal & Stadelmann (2021). «Noisy labels, missing labels: A survey of un-, weakly-, and semi-supervised learning methods for industrial vision applications». SDS 2021.

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# 1. Lessons learned 1/2

### Deployment

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• Should include continuous learning

### Symbolic image: a CNN in (optical) hardware (Lin et al., 2018).

Detectors

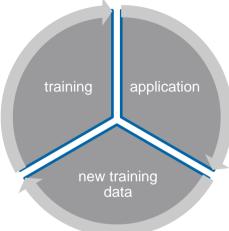
Lin, Rivenson, Yardimci, Veli, Luo, Jarrahi & Oczan (2018). «All-optical machine learning using diffractive deep neural networks». Science, 26. Jul 2018.

Diffractive Deep Network



Input Object





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# 2. Music scanning – methodology (further details) Reconstructing labeled bounding boxes

### Finding object instances:

Set all values of the energy prediction below a certain threshold to zero (watershed step).
 Perform a connected component analysis on this output --> the center of mass for every connected component is defined to be the position of one detected object.

### Predicting the class:

3. For each connected component look up the corresponding class predictions for of all its pixels and use the majority vote.

### Predicting object size:

4. For each connected component look up the corresponding size predictions for of all its pixels and compute the mean.





# Lessons learned 2/2



### (r) angreenat (celliot

### Loss shaping

Usually necessary to enable learning of very complex target functions

"Initially, the training was unstable [...] if directly trained on the combined weighted loss. Therefore, we now train [...] on each of the three tasks separately. We further observed that while the network gets trained on the bounding box prediction and classification, the energy level predictions get worse. To avoid this, the network is fine-tuned only for the energy level

loss [...]. Finally, the network is retrained on the combined task [...] for a few thousand iterations [...]."

This includes **encoding expert knowledge** manually into the model architecture or training setup

"The **size of the anomaly** in classifying balloon catheters as good or bad is **quite decisive**. Thus, rescaling the training images is not allowed, and we used a fixed size window around the center of each defect to extract the training images."

Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.