

Industrielle Anwendungsmöglichkeiten für Deep Learning-basierte Künstliche Intelligenz

*Endress+Hauser Technologieforum, Sternenhof Auditorium, Reinach BL
01. Februar 2019*

Thilo Stadelmann



Why?



Why?



arXiv monthly submission rates



Why?



arXiv monthly submission rates



Forbes Billionaires Innovation Leadership Money Consumer Industry Lifestyle

GPU TECHNOLOGY CONFERENCE

EUROPE / 9-11 OKTOBER, 2016
DER WICHTIGSTE EVENT ZU KÜNSTLICHER INTELLIGENZ
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10 Amazing Examples Of How Deep Learning AI Is Used In Practice?

Bernard Marr Contributor
Enterprise & Cloud

You may have heard about deep learning and felt like it was an area of data science that is incredibly intimidating. How could you possibly get machines to learn like humans? And, an even scarier notion for some, why would we want machines to exhibit human-like behavior? Here, we look at 10 examples of how deep learning is used in practice that will help you visualize the potential.

“The growth of deep-learning models is expected to accelerate and create even more innovative applications in the next few years.”

Idea: Add depth to learn features automatically

Classical image processing

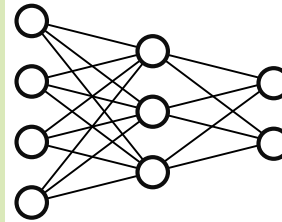


Feature extraction
(SIFT, SURF, LBP, HOG, etc.)

(0.2, 0.4, ...)

(0.4, 0.3, ...)

Classification
(SVM, neural network, etc.)



Container ship

Tiger

...

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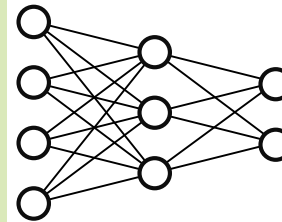


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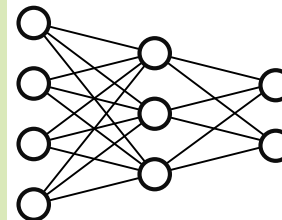
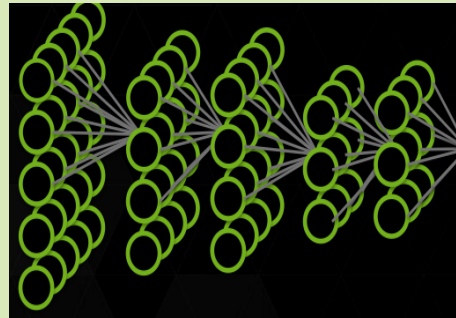
Tiger

...

Using Convolutional
Neural Networks
(CNNs)



Takes raw pixels in, learns
features automatically!



Container ship

Tiger

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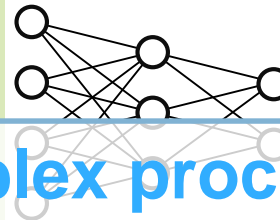
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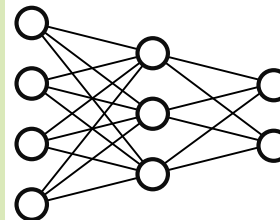
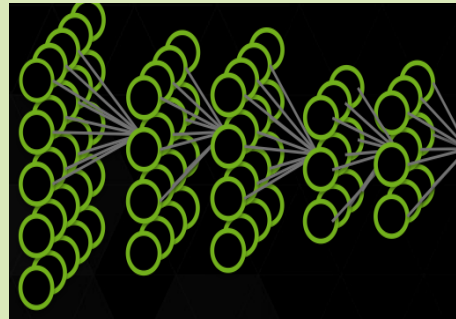
Tiger

Automation of complex processes
based on (high-dimensional) sensor input

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Container ship

Tiger

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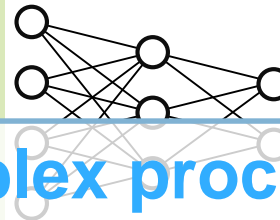
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Container ship

Tiger

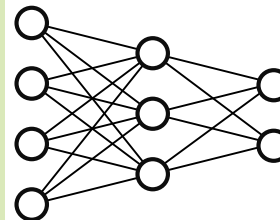
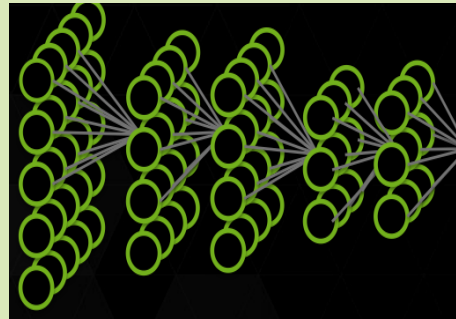
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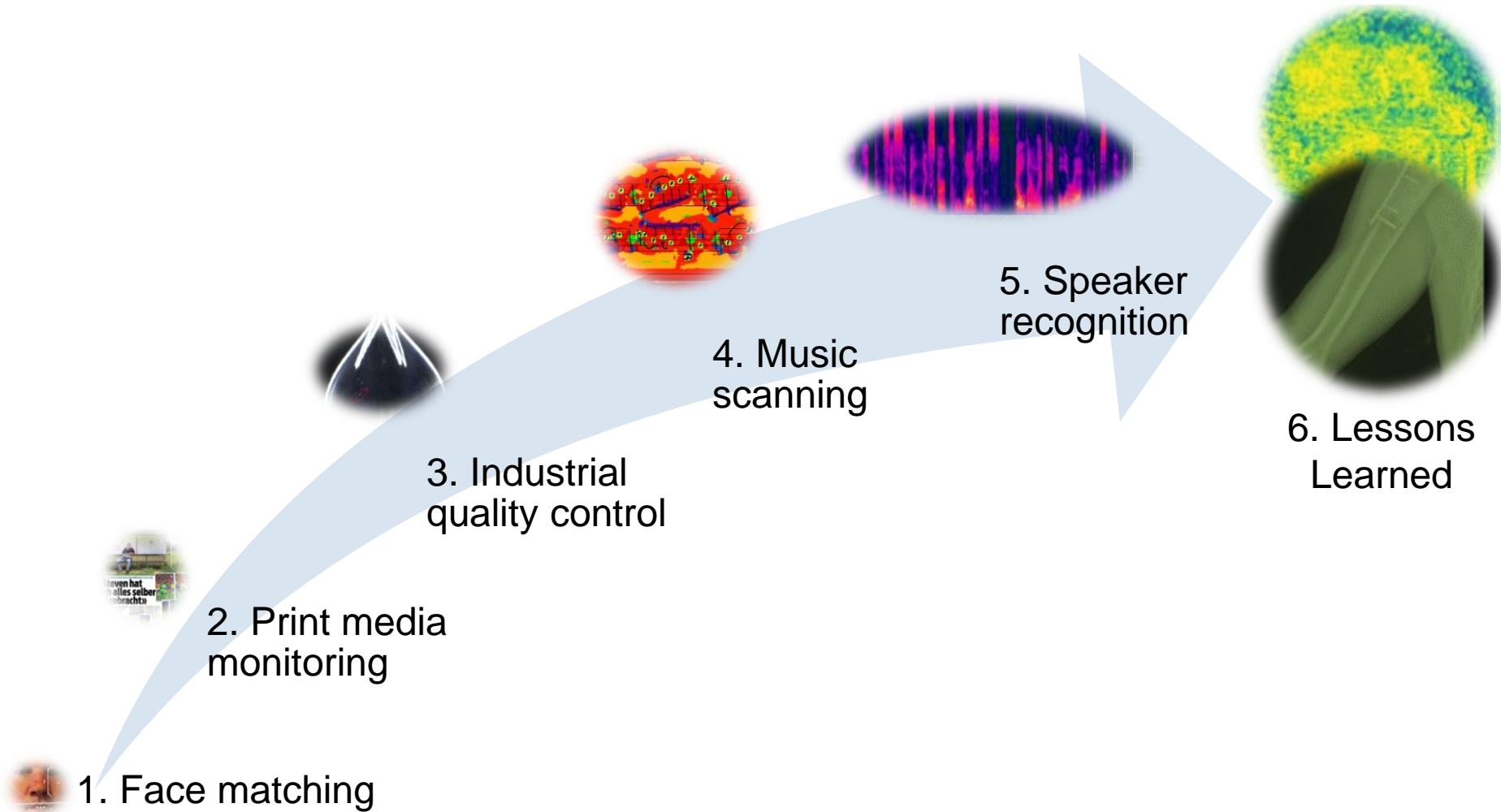


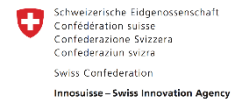
Container ship

Tiger

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Agenda






1. Face matching

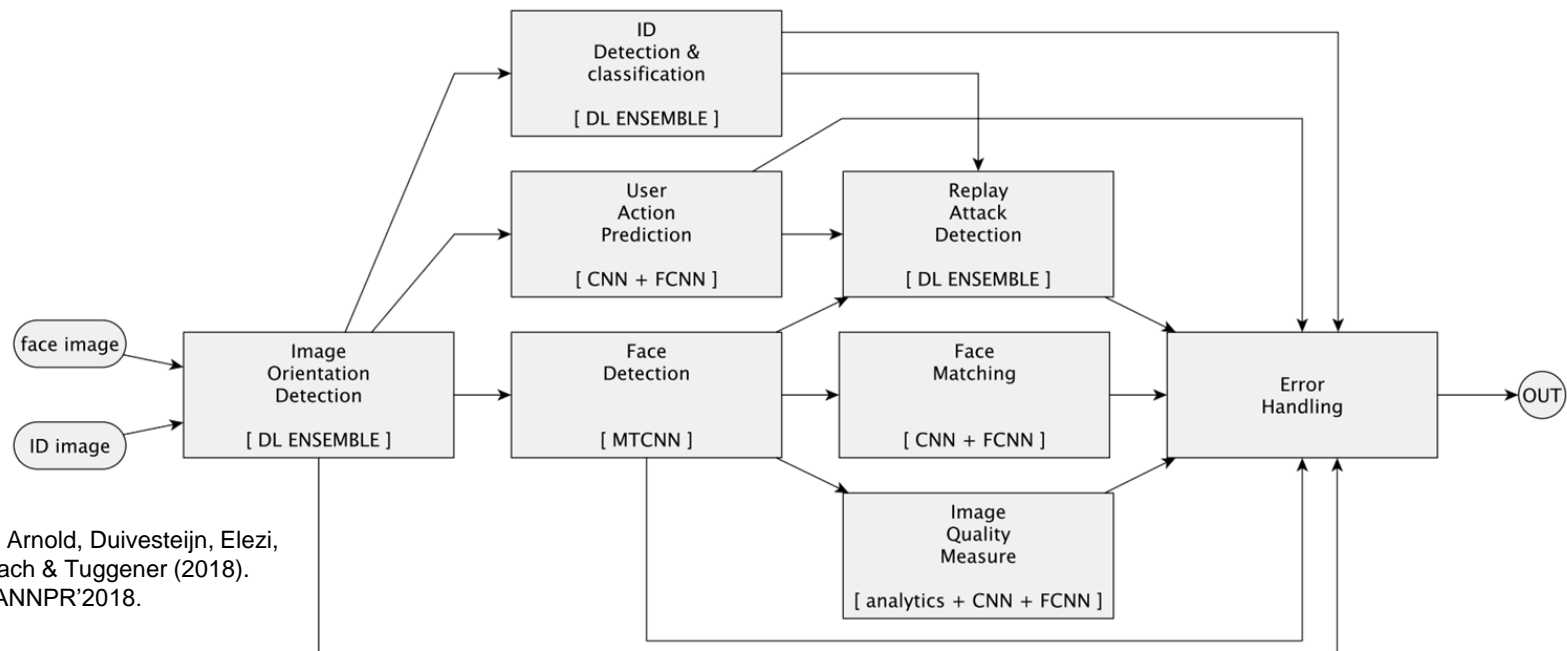
1. Face matching



 DEEPIIMPACT

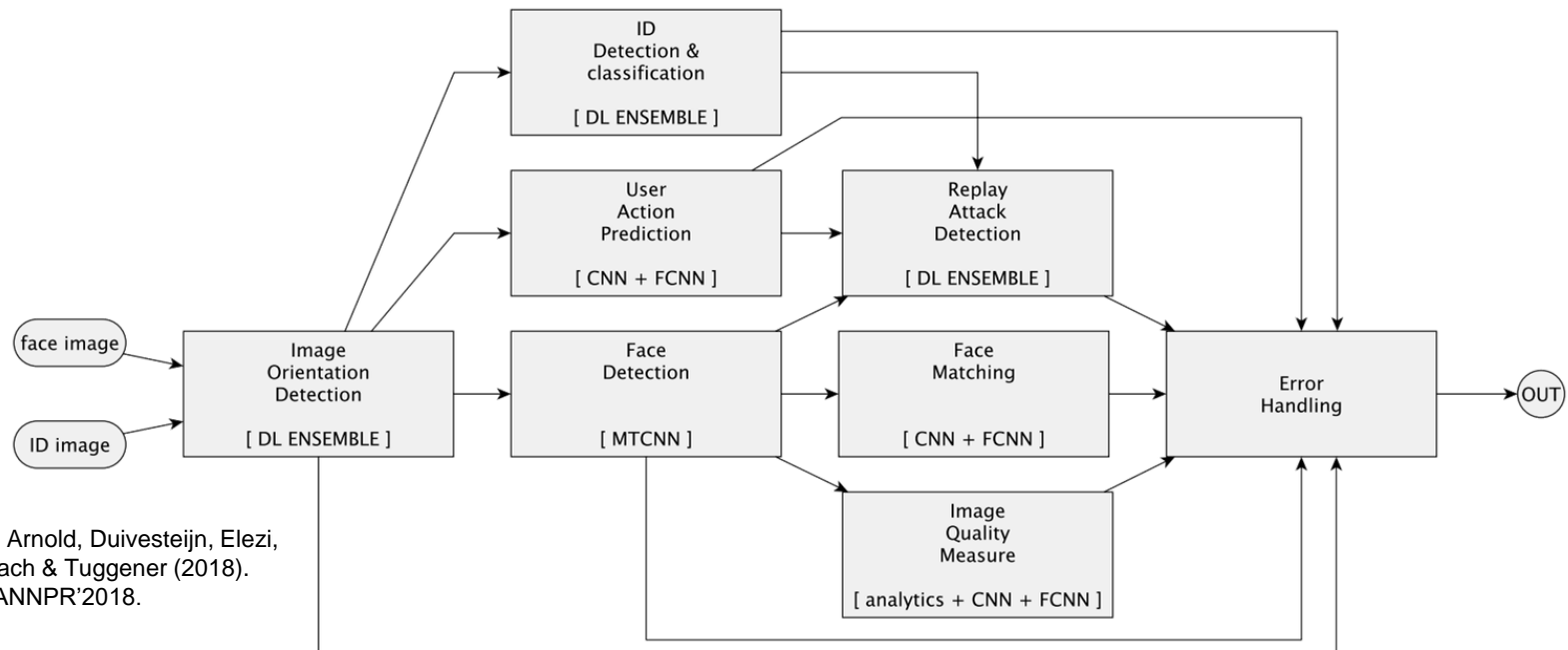
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1. Face matching – challenges & solutions



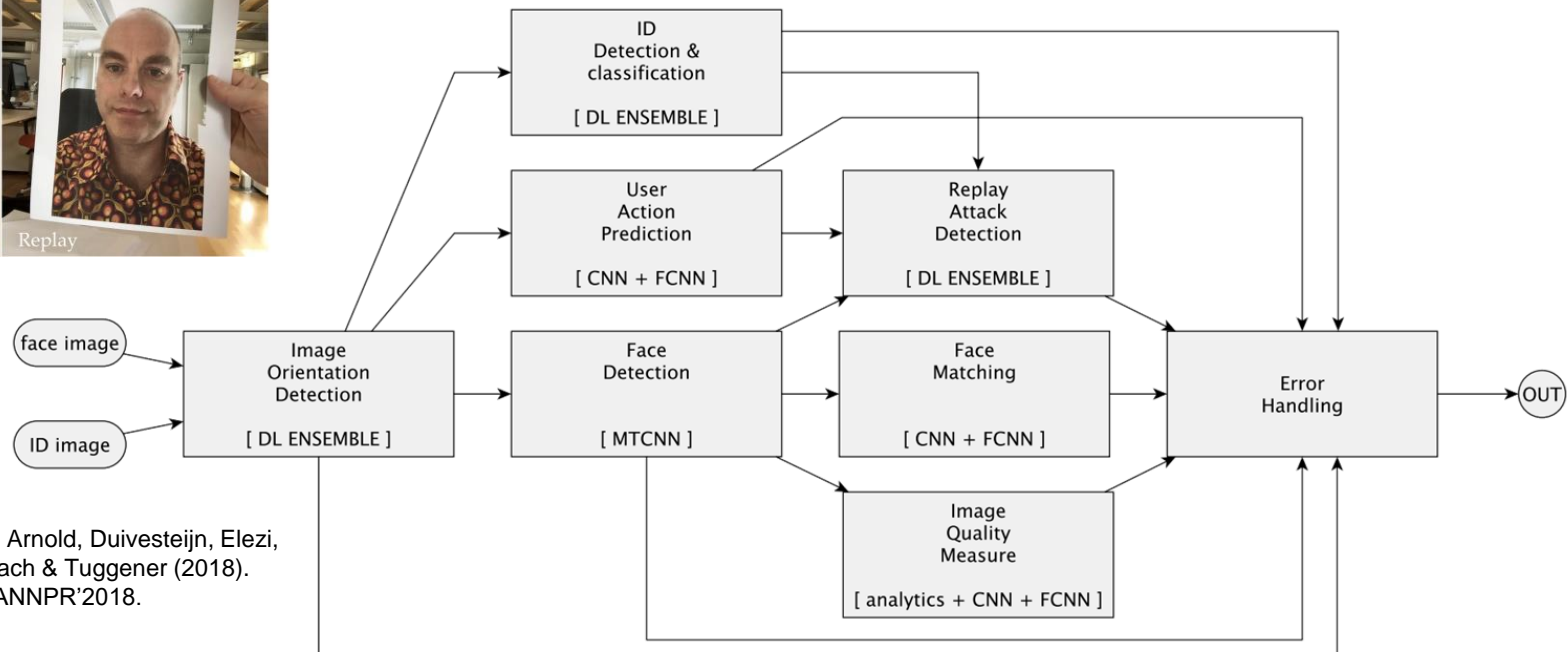
Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

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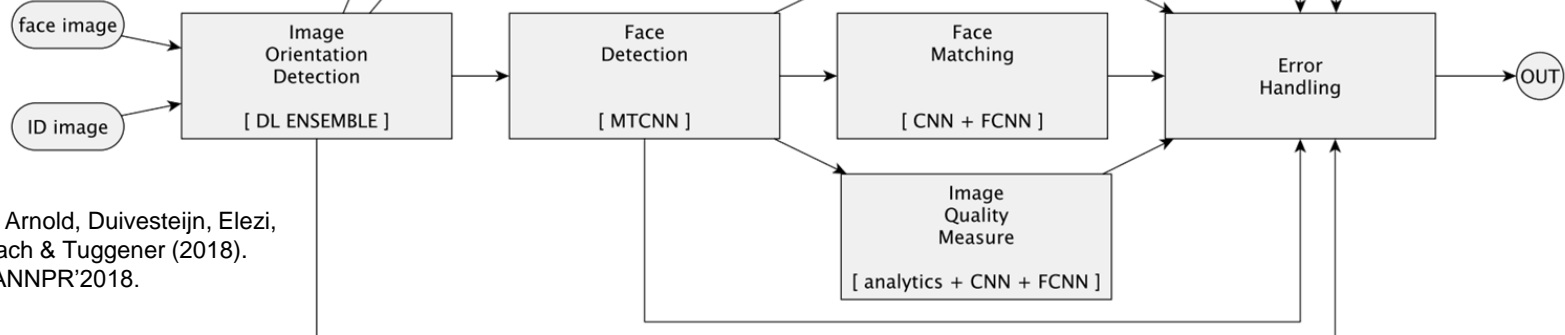
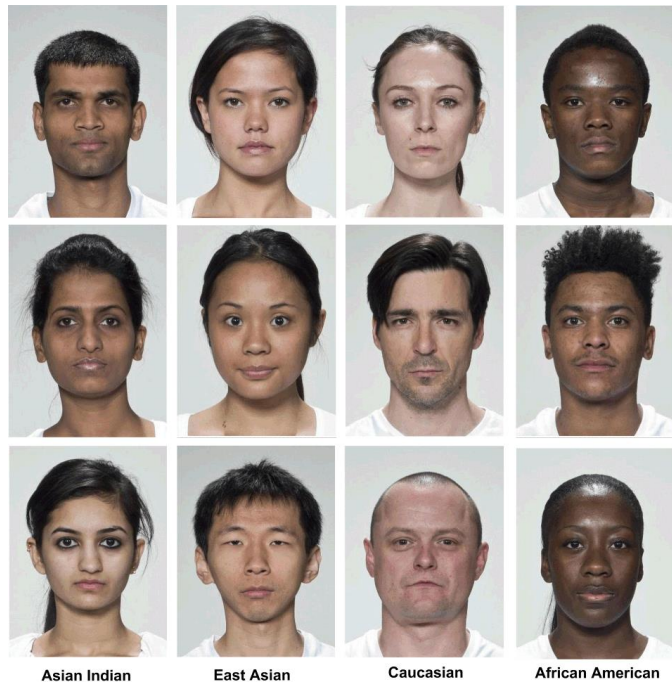
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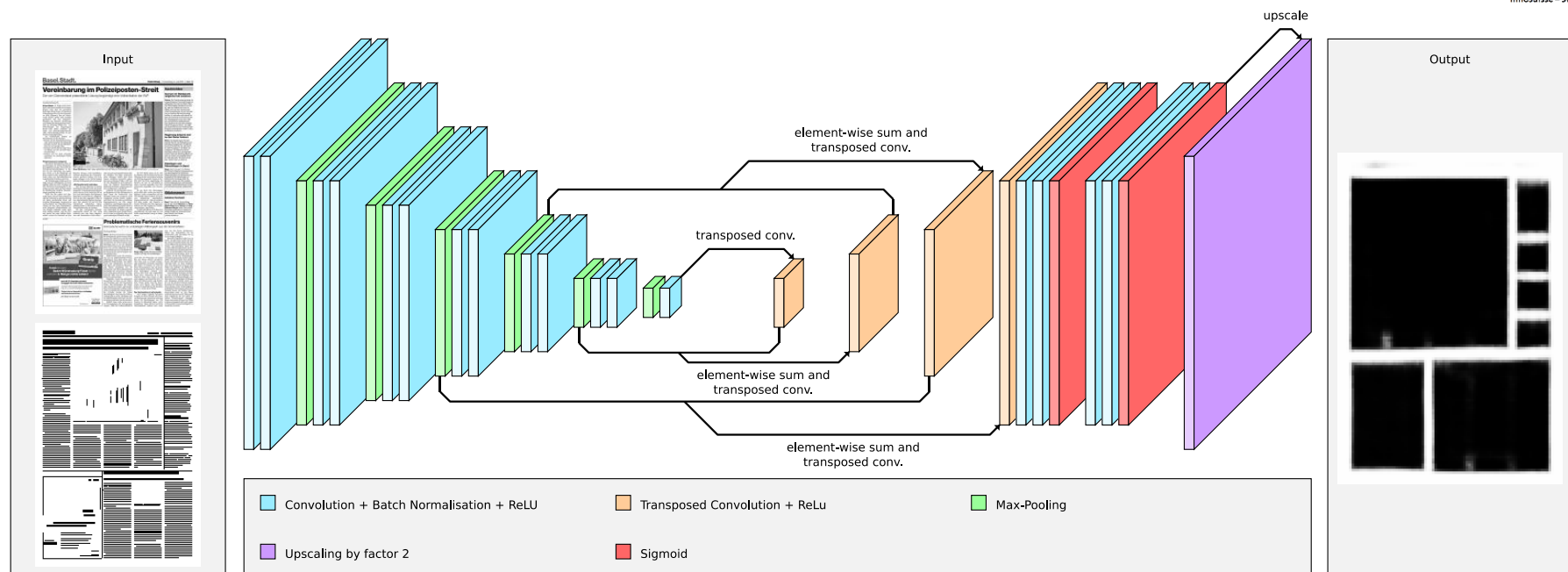
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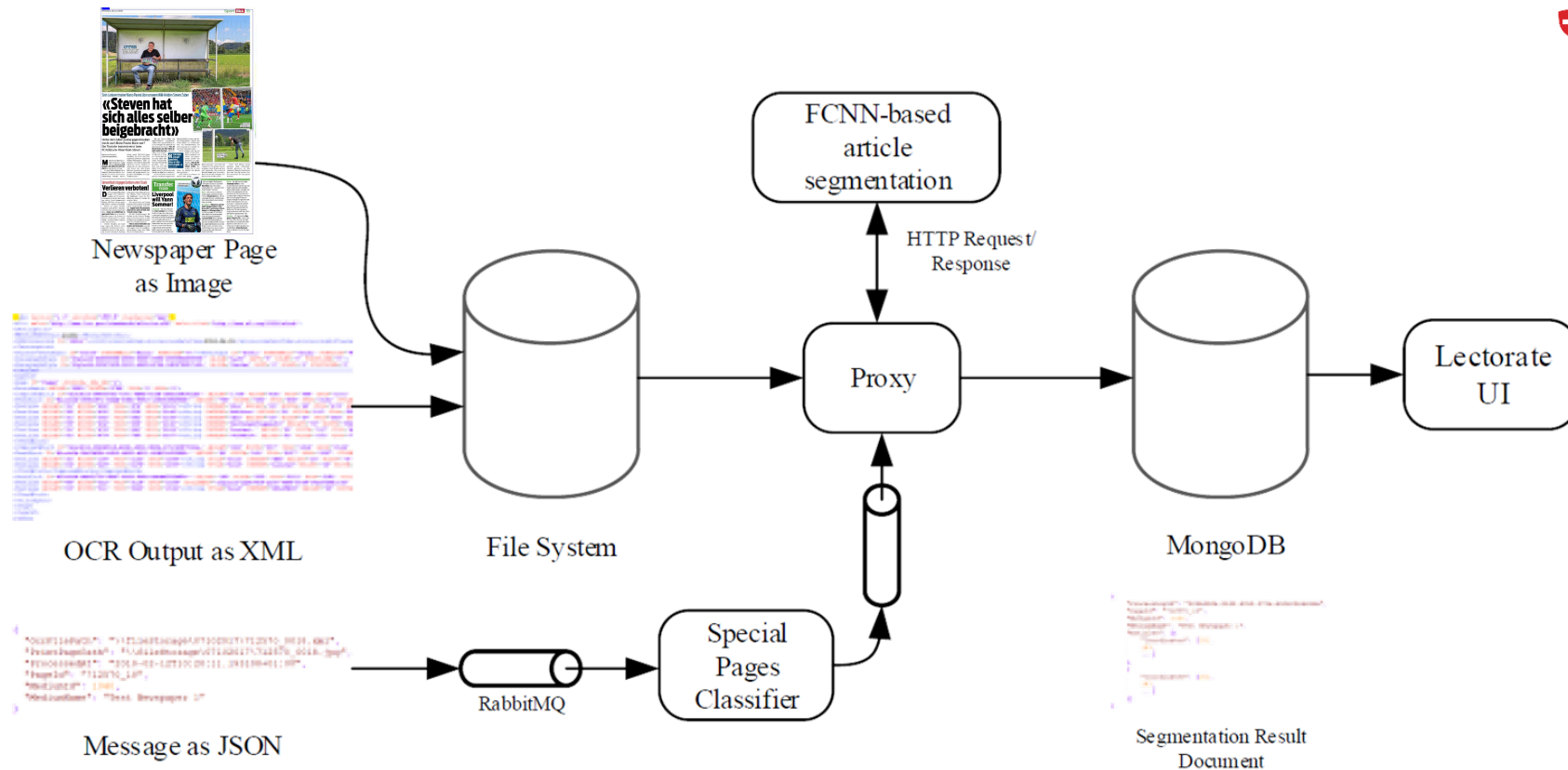
Stadelmann, Amirian, Arabaci, Arnold, Duivesteijn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

2. Print media monitoring – ML solution



Meier, Stadelmann, Stampfli, Arnold & Cieliebak (2017). «Fully Convolutional Neural Networks for Newspaper Article Segmentation». ICDAR'2017.
Stadelmann, Tolkachev, Sick, Stampfli & Dürri (2018). «Beyond ImageNet - Deep Learning in Industrial Practice». In: Braschler et al., «Applied Data Science», Springer.

2. Print media monitoring – deployment

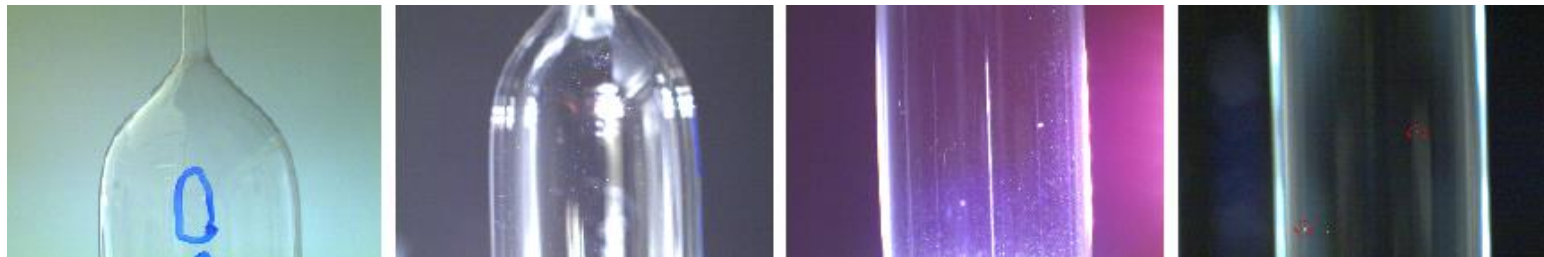


Stadelmann, Amirian, Arabaci, Arnold, Duivesteyn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

3. Industrial quality control

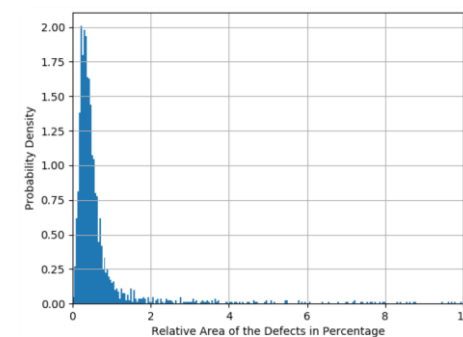
Task

- Reliably **sort out faulty balloon catheters** in image-based production quality control



Challenges

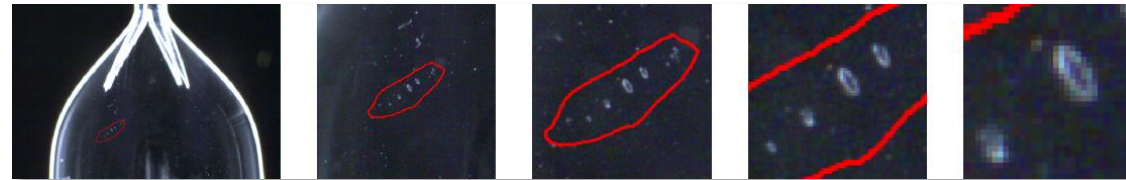
- Non-natural** image source, class **imbalance**, **optical** conditions, **variation** in defect size & shape



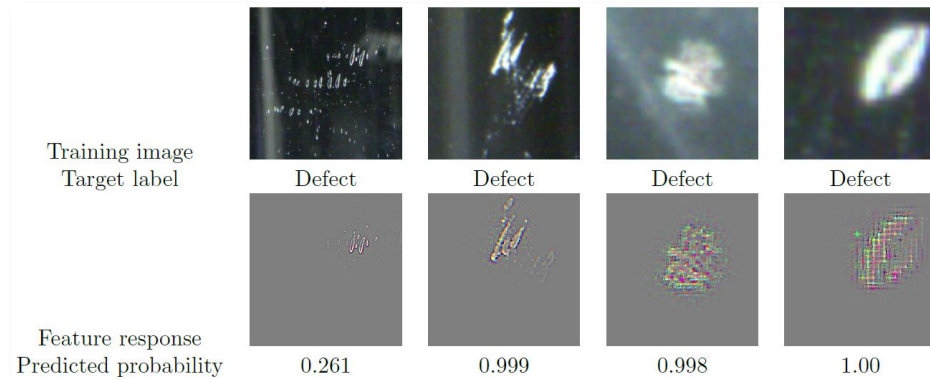
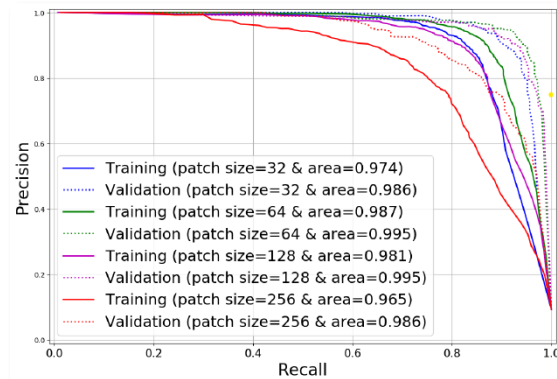
3. Industrial quality control – baseline results

Ingredients

- Weighted loss
- Defect cropping
- Careful customization



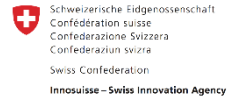
Interm results





3. Industrial quality control – recent results (Work in progress)

- Human performance isn't flawless



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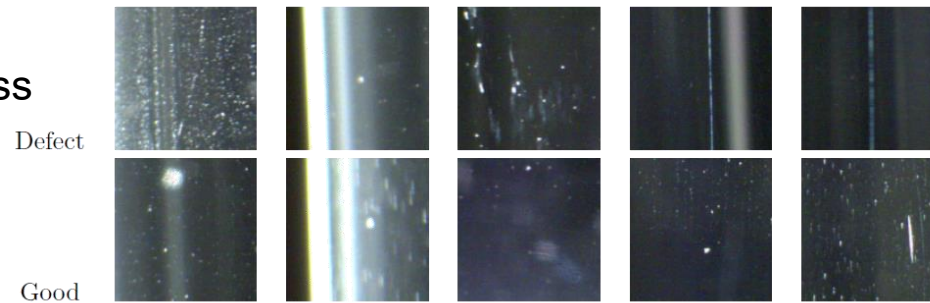


Figure 2: Samples of failure cases in classification. The shown *defect* samples in the table are not recognized as a defects, and the *good* images are misclassified as defects.

3. Industrial quality control – recent results (Work in progress)

- Human performance isn't flawless
- Tailoring pays off

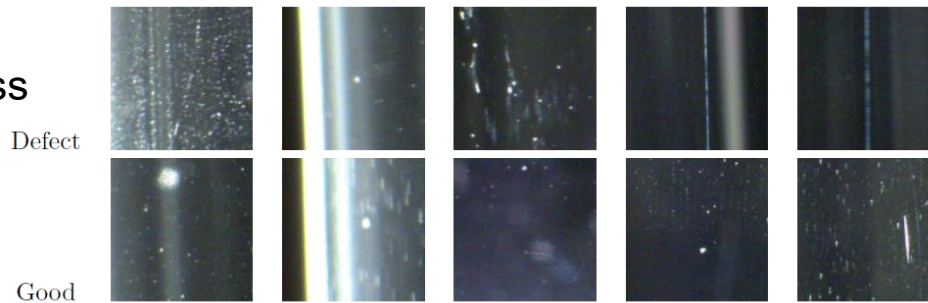
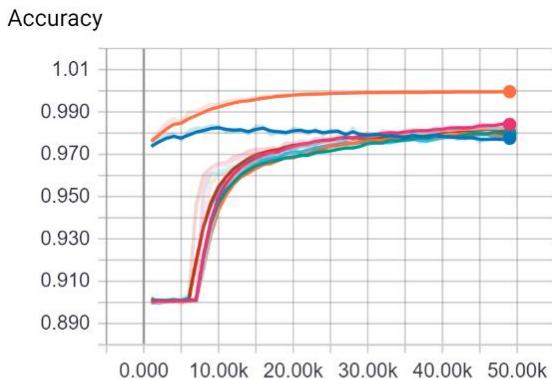


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Name	Smoothed Value	Value	Step	Time	Relative
QualitAI_VGG19_Full_Pretrained\train	0.9996	0.9996	49.00k	Tue Jan 22, 02:32:13	8h 30m 56s
QualitAI_VGG19_Full_Pretrained\validation	0.9776	0.9783	49.00k	Tue Jan 22, 02:32:24	8h 30m 56s
QualitAI_VGG19_Full_Random\train	0.9841	0.9841	49.00k	Thu Jan 24, 19:28:02	10h 29m 2s
QualitAI_VGG19_Full_Random\validation	0.9798	0.9798	49.00k	Thu Jan 24, 19:28:14	10h 29m 2s
QualitAI_VGG19_Half\train	0.9827	0.9835	49.00k	Thu Jan 24, 13:01:47	4h 9m 12s
QualitAI_VGG19_Half\validation	0.9792	0.9798	49.00k	Thu Jan 24, 13:01:54	4h 9m 11s
QualitAI_VGG19_Quarter\train	0.9817	0.9823	49.00k	Thu Jan 24, 10:53:52	2h 17m 21s
QualitAI_VGG19_Quarter\validation	0.9791	0.9806	49.00k	Thu Jan 24, 10:53:56	2h 17m 21s

3. Industrial quality control – recent results (Work in progress)

- Human performance isn't flawless
- Tailoring pays off
- Data shortage may be outsmarted

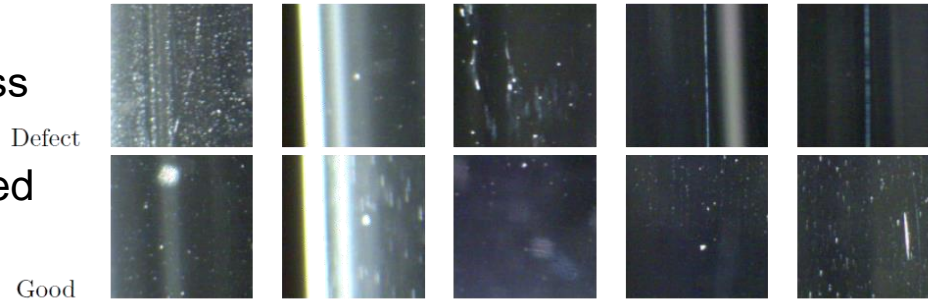
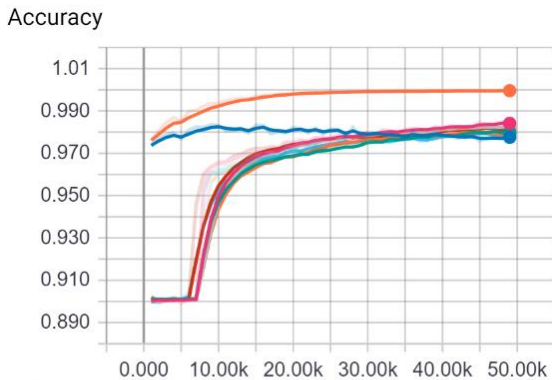
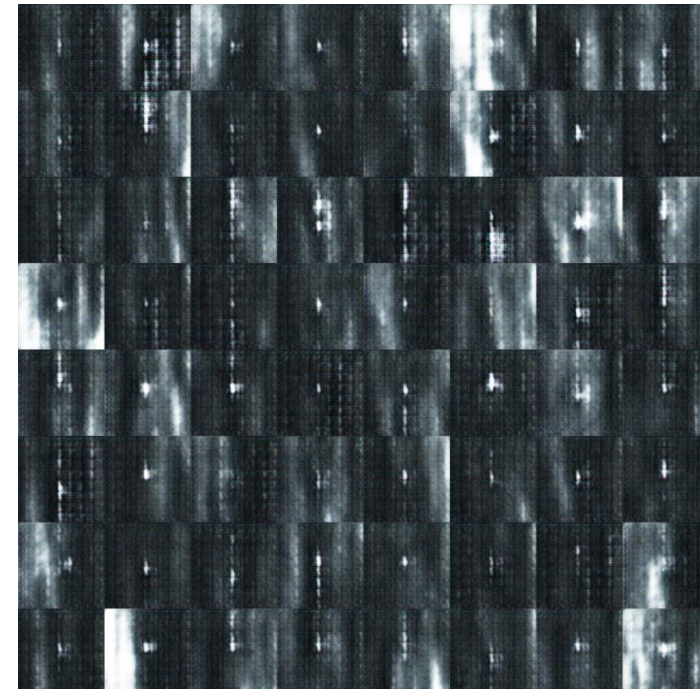


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4. Music scanning – challenges & solutions



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Tuggener, Elezi, Schmidhuber, Pelillo & Stadelmann (2018). «DeepScores – A Dataset for Segmentation, Detection and Classification of Tiny Objects». ICPR'2018.

4. Music scanning – challenges & solutions



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4. Music scanning – challenges & solutions

The image shows a musical score with several measures. A callout box highlights four specific annotations:

- (a) accidentalSharp: A sharp sign (#) placed above a note.
- (b) keySharp: A sharp sign (#) placed at the beginning of a staff.
- (c) augmentationDot: A red dot placed above a note.
- (d) articStaccatoAbove: A red dot placed above a note.

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4. Music scanning – challenges & solutions

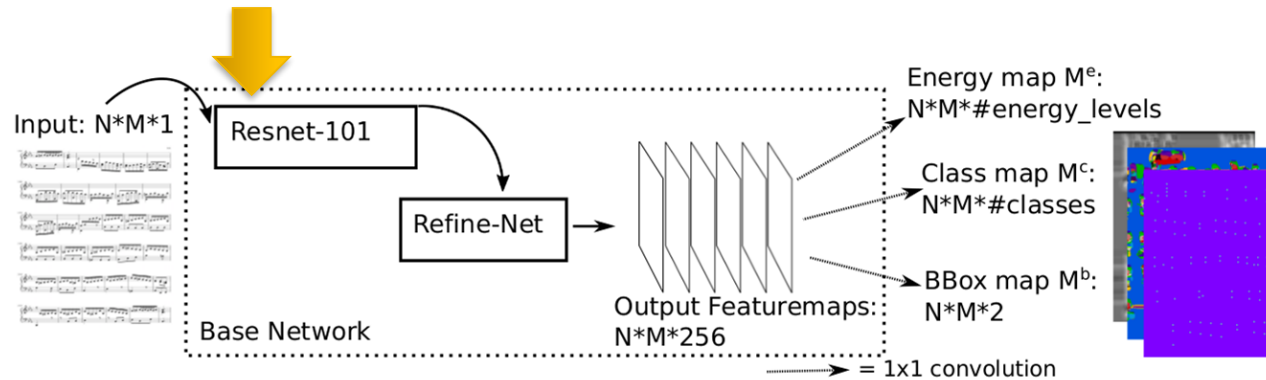
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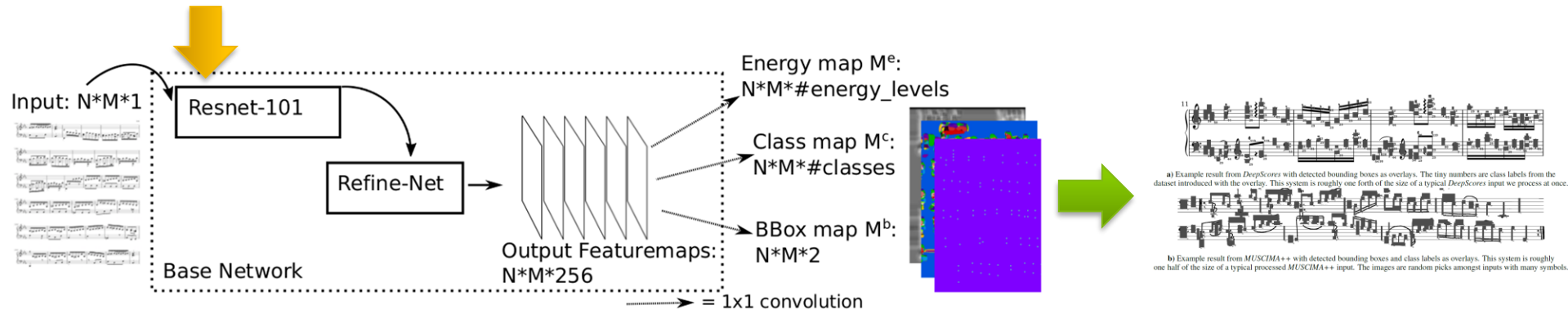
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4. Music scanning – challenges & solutions



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4. Music scanning – challenges & solutions

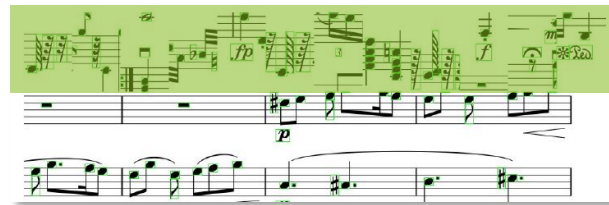


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4. Music scanning – industrialization

Recent results on **class imbalance** and **robustness** challenges

1. Added sophisticated **data augmentation** in every page's margins



2. Put additional effort (and compute) into hyperparameter **tuning** and **longer training**
3. Trained also on scanned (more **real-worldish**) scores

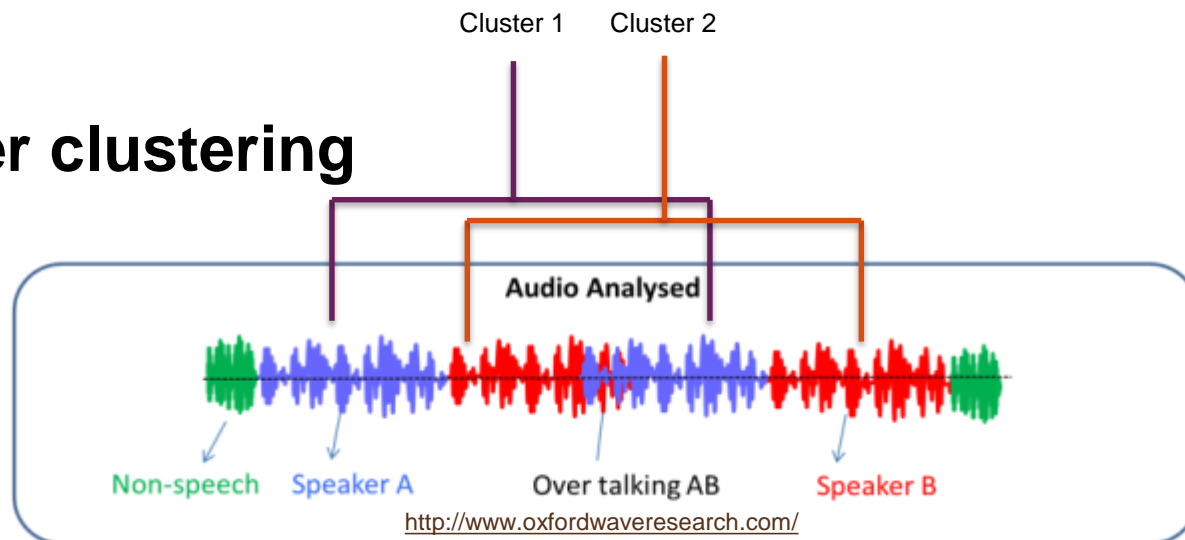


→ **Improved** our **mAP** from 16% (on purely synthetic data) **to 73%** on more challenging real-world data set (additionally, using Pacha et al.'s evaluation method as a 2nd benchmark: from 24.8% to 47.5%)

Elezi, Tuggener, Pelillo & Stadelmann (2018). «DeepScores and Deep Watershed Detection: current state and open issues». WoRMS @ ISMIR'2018.

Pacha, Hajic, Calvo-Zaragoza (2018). «A Baseline for General Music Object Detection with Deep Learning». Appl. Sci. 2018, 8, 1488, MDPI.

5. Speaker clustering

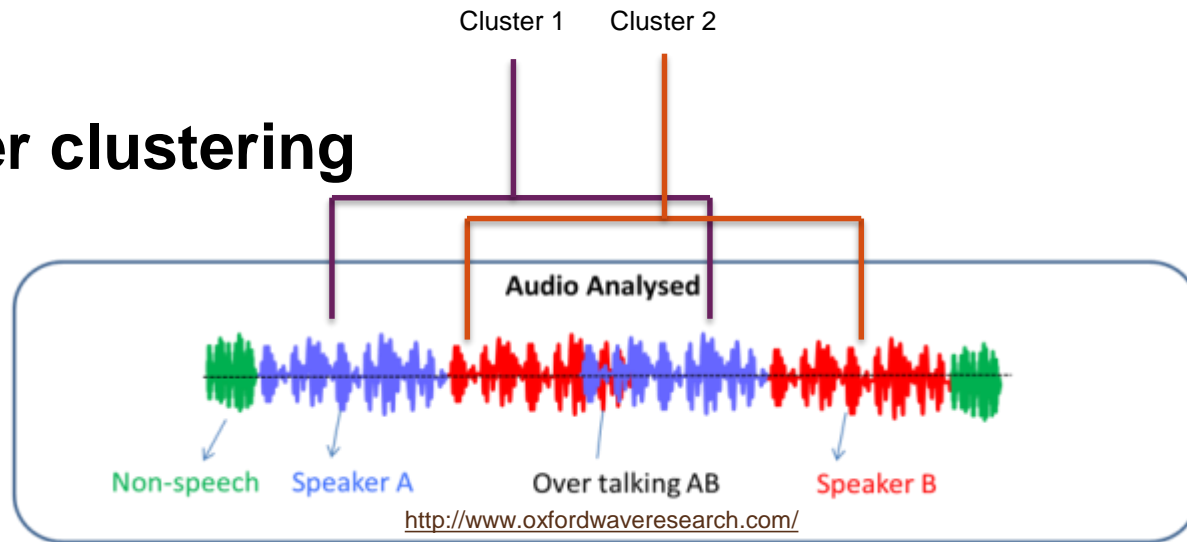


For the 630 training utterances, GMMs with 32 mixtures are built a priori, then an identification experiment is run for the 630 test utterances. It yields a satisfactory 0.5% closed set identification error.

[34]. Evaluations typically concentrate on data sets built from broadcast news/shows and meeting recordings, where diarization error rates ranging from 8% to 24% are reported [28][34][45]. These results are confirmed by more recent

The hypothesis of this paper is: the techniques originally developed for speaker verification and identification are not suitable for speaker clustering, taking into account the escalated difficulty of the latter task. However, the processing chain for speaker clustering is quite large – there are many potential areas for improvement. The question is: *where should improvements be made to improve the final result?*

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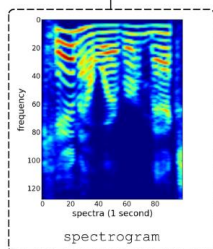
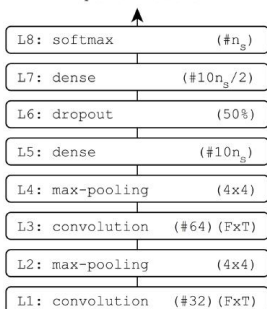
The interpretation of our results has shown that it is the stage of modeling that bears the highest potential: the inclusion of temporal context information among feature vectors is what is crucially missing there. Furthermore, the inclusion

context vector. This corresponds to a syllable length of 130 ms and is found to best capture speaker specific sounds in informal listening experiments over a range of 32–496 ms (in intervals of 16 ms). Our context vector step is one orig-

5. Speaker clustering – exploiting time information

CNN (MLSP'16)

speaker labels



Method	MR	MR (legacy)
RNN /w PKLD	2.19% ($\frac{1.25\%+2.5\%+1.25\%+3.75\%}{4}$)	4.38% (average of 4 runs)
CNN /w PKLD [24]	-	5%
CNN /w cross entropy [23]	-	5%
ν -SVM [40]	6.25%	-
GMM/MFCC [40]	12.5%	-

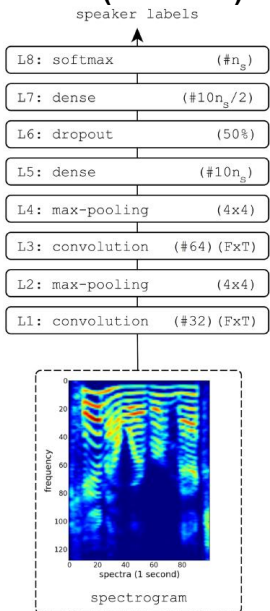
Lukic, Vogt, Dürr & Stadelmann (2016). «Speaker Identification and Clustering using Convolutional Neural Networks». MLSP'2016.

Lukic, Vogt, Dürr & Stadelmann (2017). «Learning Embeddings for Speaker Clustering based on Voice Equality». MLSP'2017.

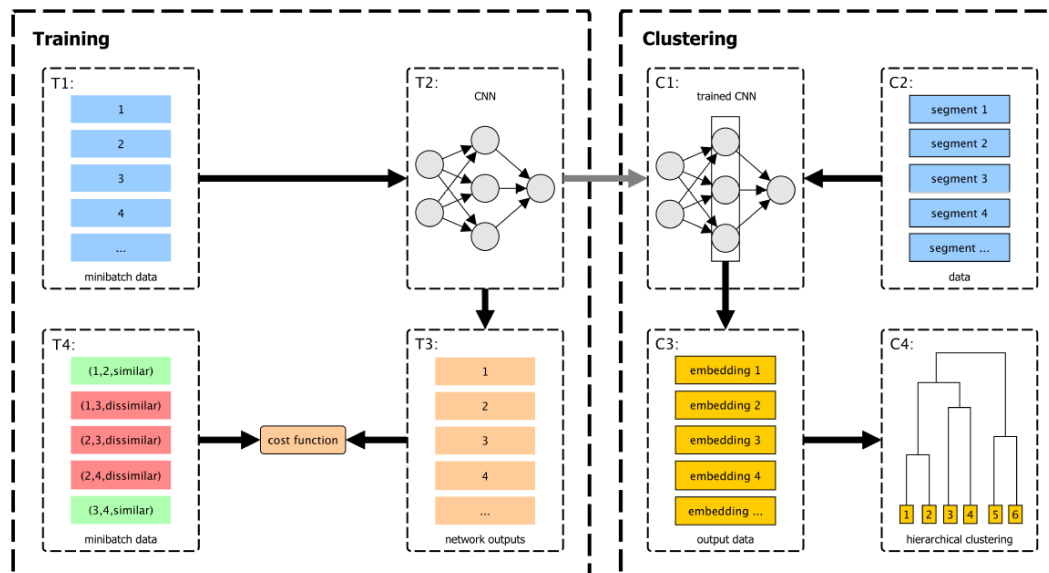
Stadelmann, Glinski-Haefeli, Gerber & Dürr (2018). «Capturing Suprasegmental Features of a Voice with RNNs for Improved Speaker Clustering». ANNPR'2018.

5. Speaker clustering – exploiting time information

CNN (MLSP'16)



CNN & clustering-loss (MLSP'17)



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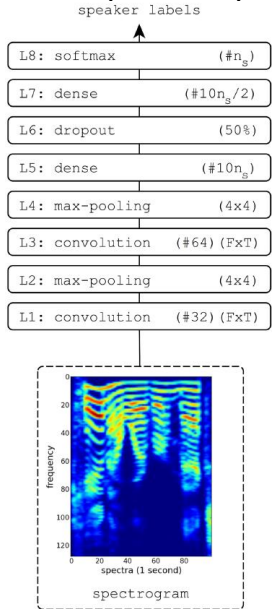
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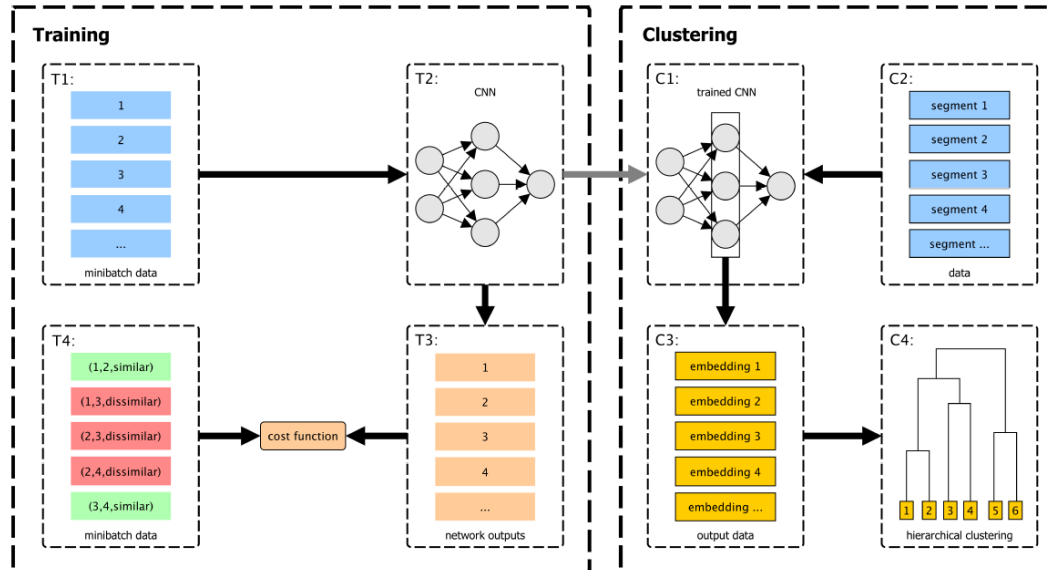
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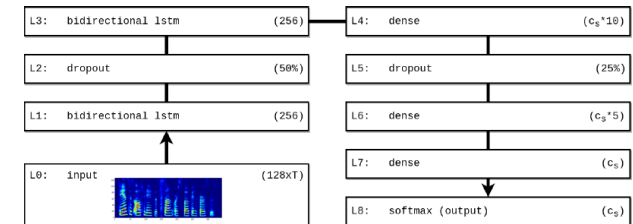
CNN (MLSP'16)



CNN & clustering-loss (MLSP'17)



RNN & clustering-loss (ANNPR'18)



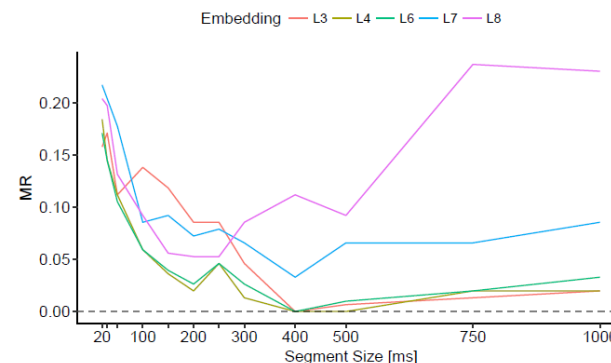
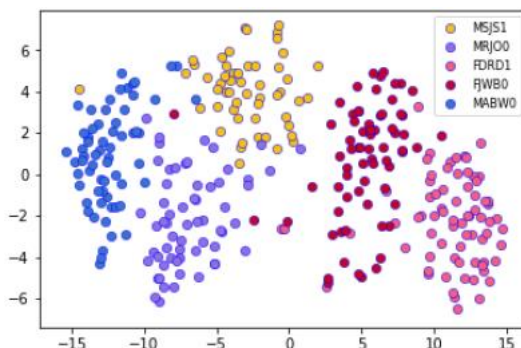
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ν -SVM [40]	6.25%	-
GMM/MFCC [40]	12.5%	-

Lukic, Vogt, Dürr & Stadelmann (2016). «Speaker Identification and Clustering using Convolutional Neural Networks». MLSP'2016.

Lukic, Vogt, Dürr & Stadelmann (2017). «Learning Embeddings for Speaker Clustering based on Voice Equality». MLSP'2017.

Stadelmann, Glinski-Haefeli, Gerber & Dürr (2018). «Capturing Suprasegmental Features of a Voice with RNNs for Improved Speaker Clustering». ANNPR'2018.

5. Speaker clustering – learnings & future work



«Pure» voice modeling seems largely solved

- RNN **embeddings work well** (see t-SNE plot of single segments)
- RNN model robustly exhibits *the predicted* «**sweet spot**» for the used **time information**
- Speaker clustering on clean & reasonably long input works **an order of magnitude better** (*as predicted*)
- Additionally, using a smarter clustering algorithm on top of embeddings makes **clustering on TIMIT as good as identification** (see ICPR'18 paper on dominant sets)

Future work

- Make models robust on **real-worldish data** (noise and more speakers/segments)
- Exploit findings for robust reliable **speaker diarization**
- **Learn** embeddings and the clustering algorithm **end to end**

Hibraj, Vascon, Stadelmann & Pelillo (2018). «Speaker Clustering Using Dominant Sets». ICPR'2018.

Meier, Elezi, Amirian, Dürr & Stadelmann (2018). «Learning Neural Models for End-to-End Clustering». ANNPR'2018.

6. Lessons learned – model interpretability

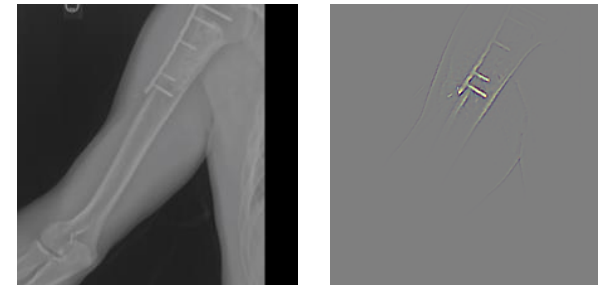
Interpretability is required.

- Helps the developer in «debugging», needed by the user to trust
→ visualizations of learned features, training process, learning curves etc. should be «always on»

negative X-ray



positive X-ray



Stadelmann, Amirian, Arabaci, Arnold, Duivesteyn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «*Deep Learning in the Wild*». ANNPR'2018.
Schwartz-Ziv & Tishby (2017). «*Opening the Black Box of Deep Neural Networks via Information*».
<https://distill.pub/2017/feature-visualization/>, <https://stanfordmlgroup.github.io/competitions/mura/>

6. Lessons learned – model interpretability

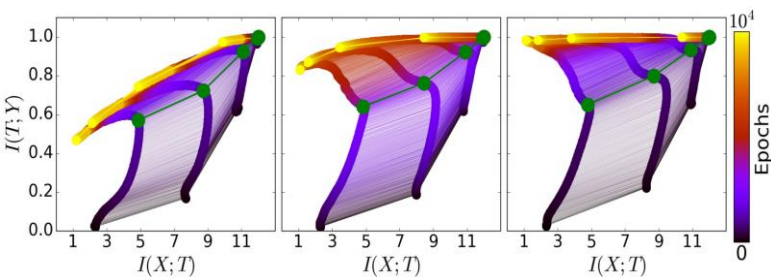
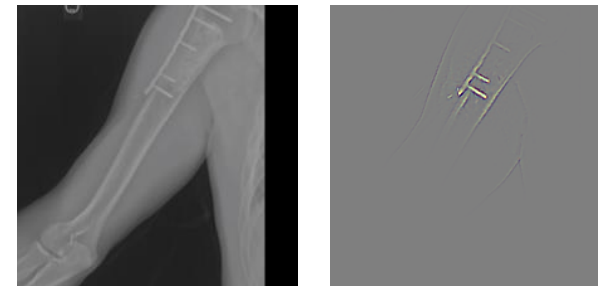
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positive X-ray



DNN training on the Information Plane

Stadelmann, Amirian, Arabaci, Arnold, Duivesteyn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

Schwartz-Ziv & Tishby (2017). «Opening the Black Box of Deep Neural Networks via Information».

<https://distill.pub/2017/feature-visualization/>, <https://stanfordmlgroup.github.io/competitions/mura/>

6. Lessons learned – model interpretability

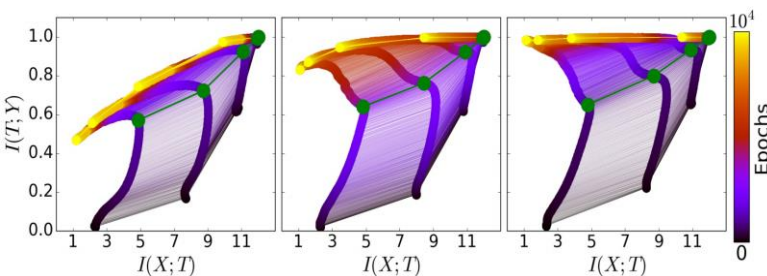
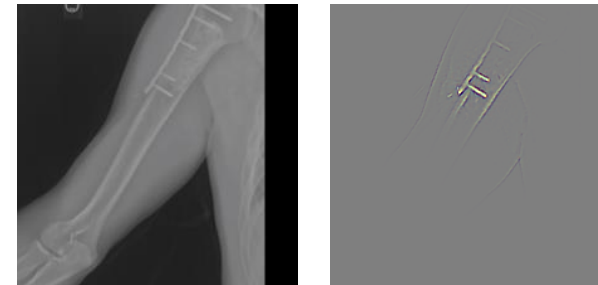
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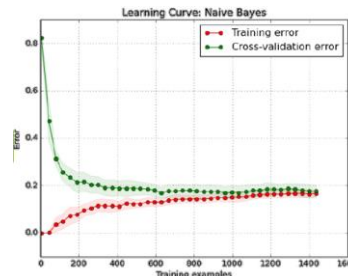
negative X-ray



positive X-ray



DNN training on the Information Plane



a learning curve

Stadelmann, Amirian, Arabaci, Arnold, Duivesteyn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.

Schwartz-Ziv & Tishby (2017). «Opening the Black Box of Deep Neural Networks via Information».

<https://distill.pub/2017/feature-visualization/>, <https://stanfordmlgroup.github.io/competitions/mura/>

6. Lessons learned – model interpretability

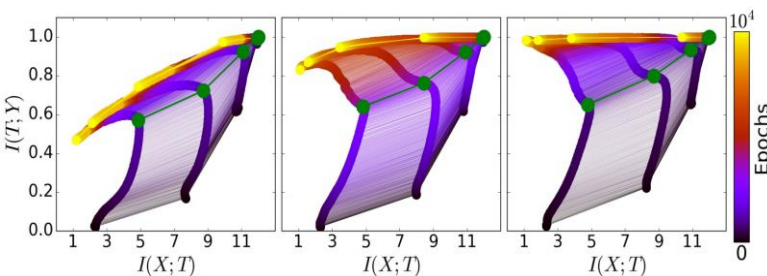
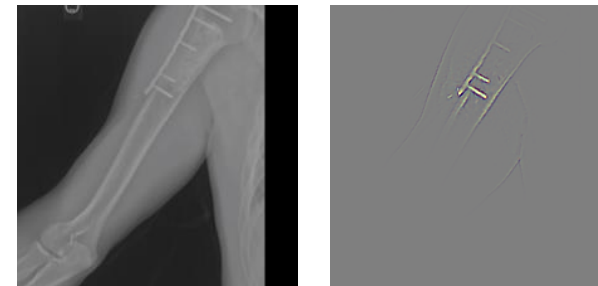
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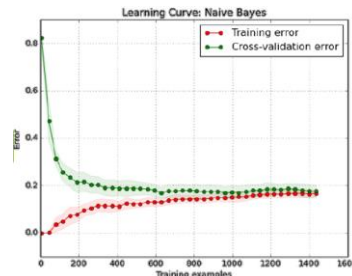
negative X-ray



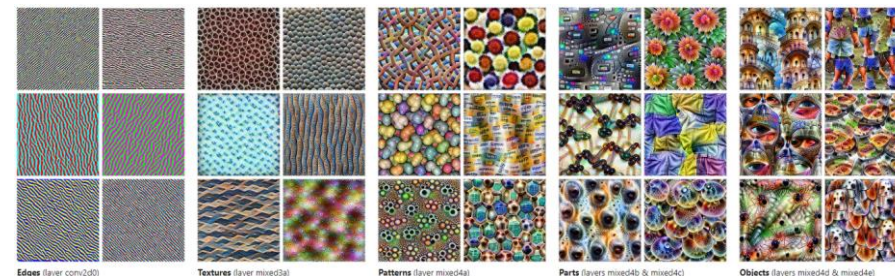
positive X-ray



DNN training on the Information Plane









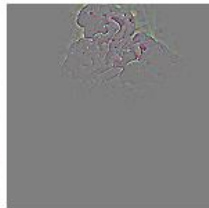
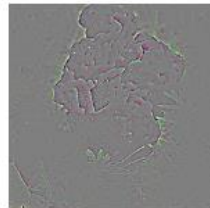
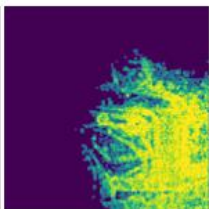
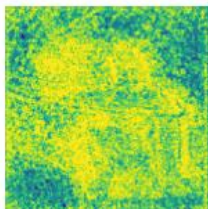
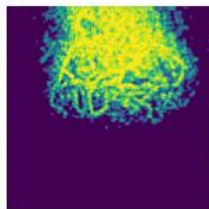
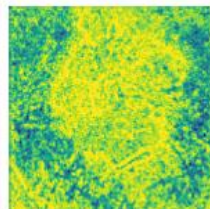
a learning curve



feature visualization

Stadelmann, Amirian, Arabaci, Arnold, Duivesteyn, Elezi, Geiger, Lörwald, Meier, Rombach & Tuggener (2018). «Deep Learning in the Wild». ANNPR'2018.
Schwartz-Ziv & Tishby (2017). «Opening the Black Box of Deep Neural Networks via Information».
<https://distill.pub/2017/feature-visualization/>, <https://stanfordmlgroup.github.io/competitions/mura/>

6. Goody – trace & detect adversarial attacks ...using average local spatial entropy of feature response maps

	Original	Adversarial	Original	Adversarial
Image:				
Feature response:				
Local spatial entropy:				

Amirian, Schwenker & Stadelmann (2018). «Trace and Detect Adversarial Attacks on CNNs using Feature Response Maps». ANNPR'2018.

Conclusions

- Deep learning **is applied** and deployed in «normal» businesses (non-AI, SME)
- It does not need big-, but some **data (effort usually underestimated)**
- DL/RL **training** for new use cases **can be tricky** (→ needs thorough experimentation)
- New **theory and visualizations** help to debug & understand
 - *the training process*
 - *individual results*

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→ Happy to answer questions & requests.

