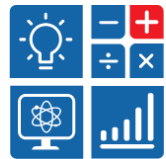


Beyond ImageNet – Deep Learning in Industrial Practice

4th Swiss Conference on Data Science, Bern, June 16, 2017

Thilo Stadelmann & Oliver Dürr



datalab

www.zhaw.ch/datalab

Introduction → Use Cases → Lessons Learned

1

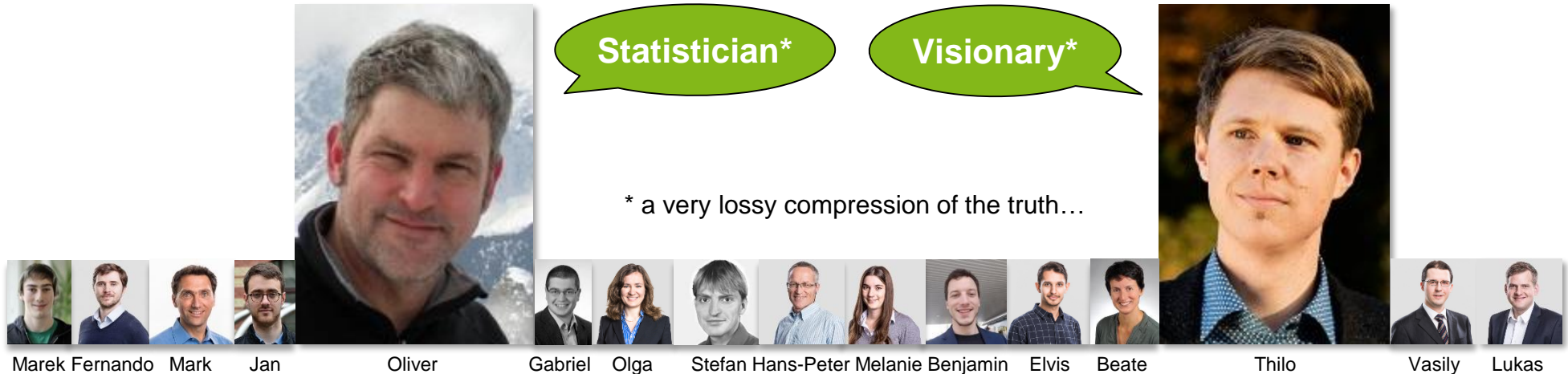
Deep Learning in a nutshell



Deep learning (DL) @ ZHAW Datalab

Initial group of 10+ researchers to start research line in 2014

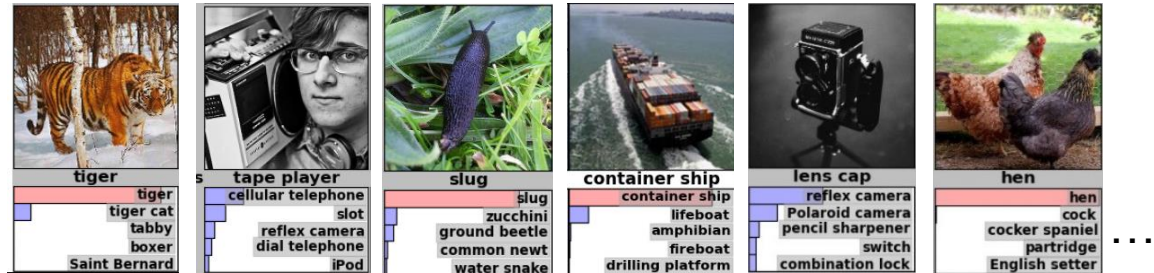
- > 11 projects since, 9 of which with industry participation (19 month duration on average, >7M CHF overall volume, several publications)
- > 20 students in thesis projects per semester (Bachelor & Master level)
- 125k CHF investment in GPU resources up to fall 2017
- New modules in Bachelor, Master, and professional education curricula



DL History: ImageNet competition starts hype



1000 classes
1 Mio. samples

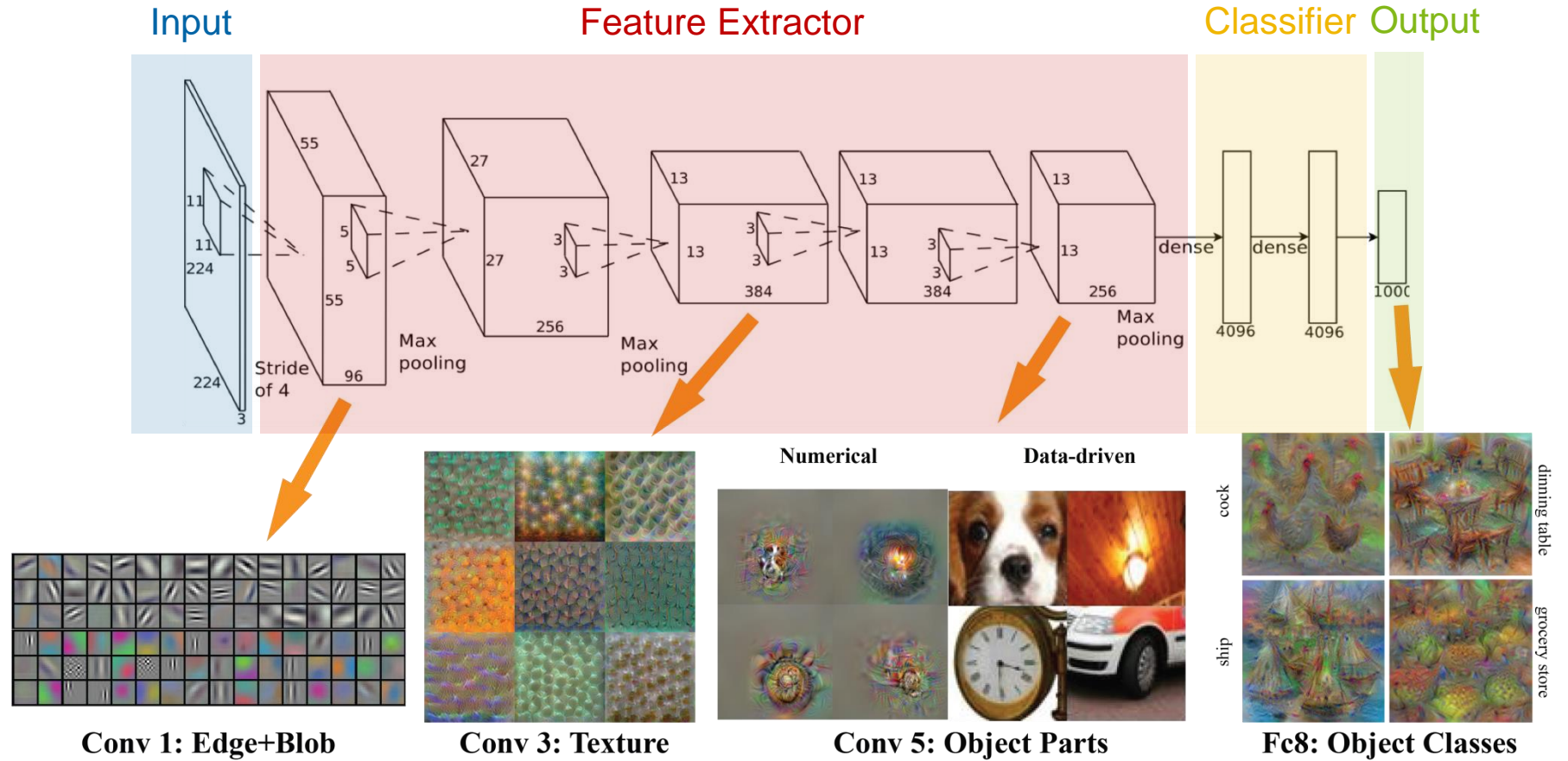


2015: computers *learned to see*

- 4.95% Microsoft (February 6, 2015)
→ surpassing human performance of 5.10%
- 4.80% Google (February 11, 2015)
- 4.58% Baidu (May 1, 2015)
- 3.57% Microsoft (December 10, 2015)

Convolutional Neural Networks

Building blocks forming a sophisticated architecture

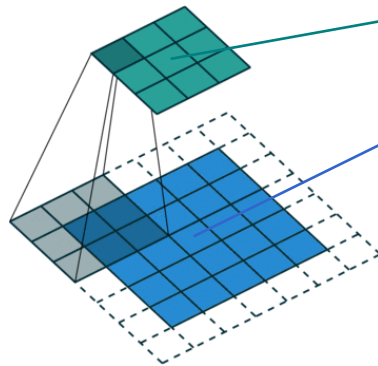


Source: http://vision03.csail.mit.edu/cnn_art/data/single_layer.png

Micro building blocks: layers

E.g., **convolutional layers**

- **Strong in finding local patterns** (i.e., 2D structure)
→ based on the idea of filtering:

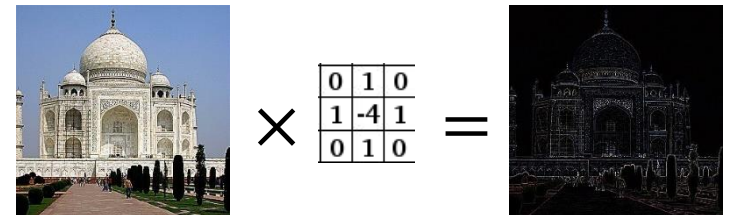
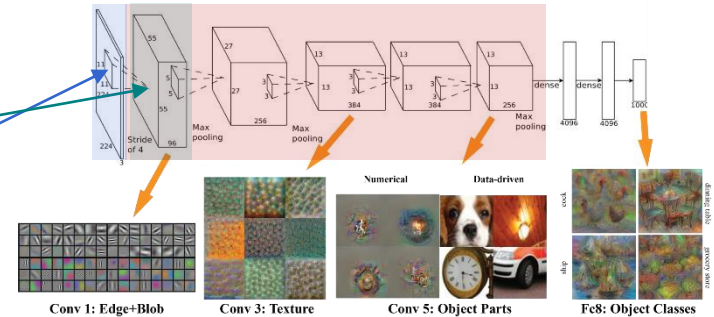


Dumoulin, Visin, «A guide to convolution arithmetic for deep learning », 2016

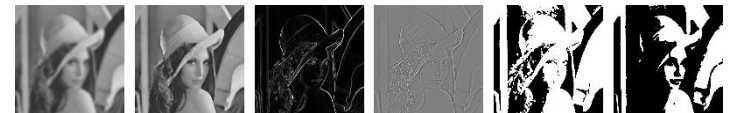
- Translation- and scale invariant
→ through down sampling (strided conv's or max pooling)
- Fast to compute
→ all possible filter locations share the 3×3 weights

Alternatives

- **Recurrent layers**, different **output layers**, ...
→ for **temporal relationships**, regression, **distribution matching**, ...



Based on <https://docs.gimp.org/en/plugin-in-convmatrix.html>

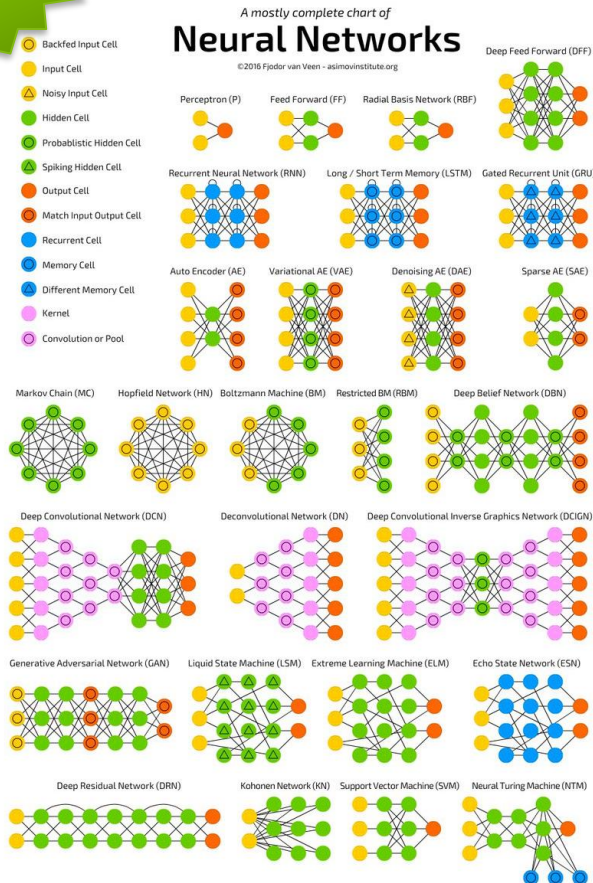


Blur Median Edge-Detect High-Pass Dilate Erode

<http://blog.teledynedalsa.com/wp-stuff/uploads/2012/05/AGhannoum-FilterExamples.png>

Macro building block: whole architectures

Example

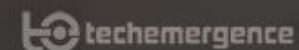


Source: <http://www.asimovinstitute.org/neural-network-zoo/>

PLAYING WITH DEEP LEARNING IS LIKE
PLAYING WITH LEGOS, YOU CAN GRAB ALL
THESE MODULES OF LEGO PIECES AND BUILD
THINGS

- Nando de Freitas

Senior Staff Research Scientist, Google

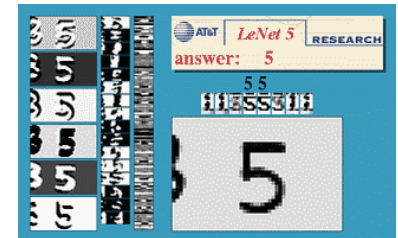
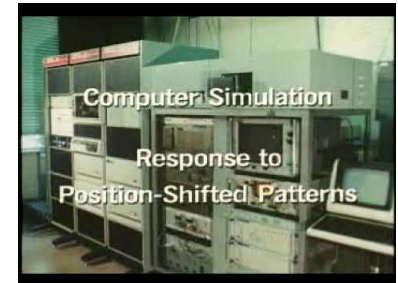


What makes CNNs work?

More history

- Biological plausibility known since 1959 (Hubel & Wiesel)
- First CNN (“Neocognitron”) in 1980 (Fukushima)
- Automatic bank check reading in 1998 (LeCun et al.)
- But: General breakthrough in computer vision only in 2012 (see above)

“...most of this progress is not just the result of more powerful hardware, larger datasets and bigger models, but mainly a consequence of new ideas, algorithms and improved network architectures”.

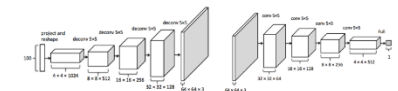


What's different now?

- **Big Data** (labeled images via the web)
- **Compute power** (consumer GPUs, i.e. NVIDIA's GeForce series)
- **Algorithmic improvements**
 - Regularization: **Dropout**
 - Optimization: **ADADELTA**
 - Trainability (“gradient flow”): **Batchnorm, ReLU**
 - Exploitation of available data: **Augmentation, transfer learning**
 - More powerful architectures: **ResNet, Fully Convolutional NN, Generative Adversarial N, YOLO, ...**



Szegedy et al., “Going Deeper with Convolutions”, 2014



Introduction → Use Cases → Lessons Learned

2

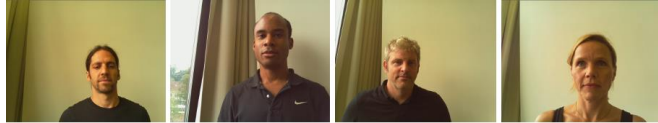
From image classification to paths less travelled

Case Study I (Limited Resources)

Face Recognition on Raspberry Pi

Architecture and Training Set

Training indoors

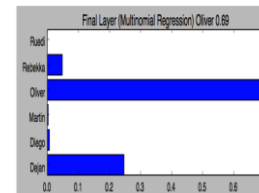
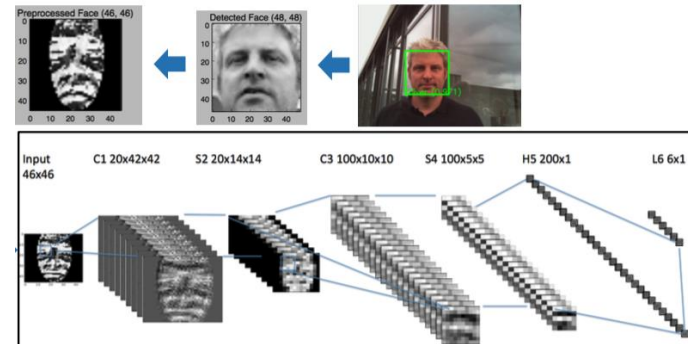


Approx. 40 images of 6 persons

Prediction done on Raspberry Pi

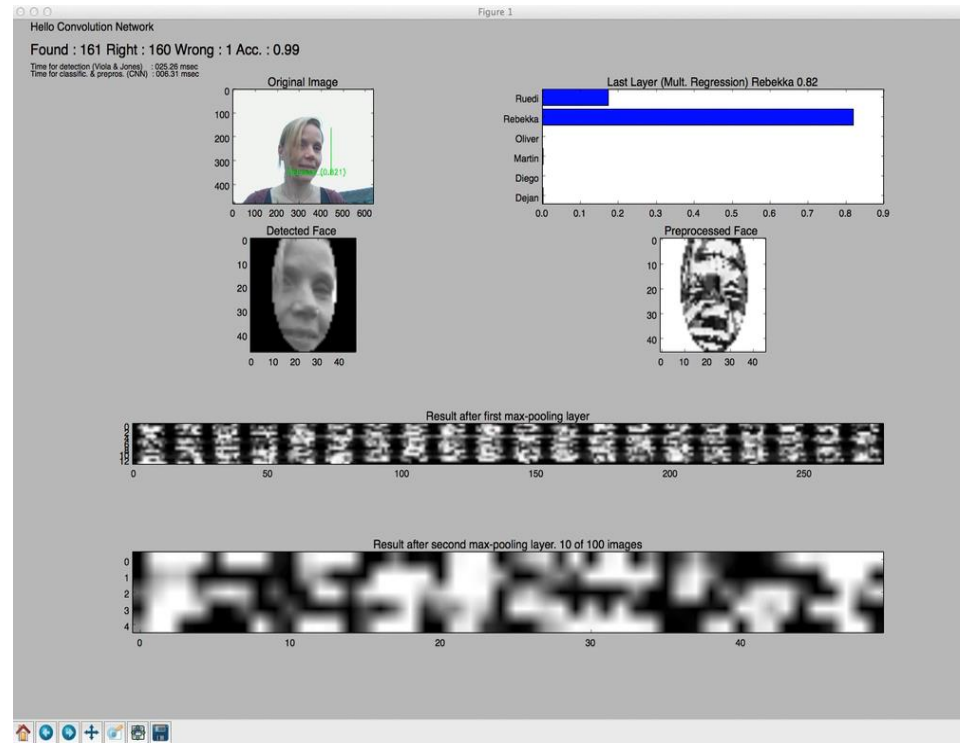


Testing outdoors



Forward pass

train on
GPU...



...predict on
Raspberry Pi



Results

Method	Accuracy	Classification Time [msec]	Enrollment Rate N_e/N	Total Time Per Face [msec]
CNN ($p_0=0.85$)	99.59%	105 +/- 8	250/278	529 +/- 64
CNN ($p_0=0.00$)	97.48%	105 +/- 8	278/278	529 +/- 64
Fisherfaces (no al.)	88.5%	54 +/- 11	278/278	511 +/- 89
Fisherfaces (al.)	96.87%	535 +/- 89	192/278	1006 +/- 18

- Faster than traditional pipeline
- No alignment needed
- Alternative implementation on Android (BA Thesis)
- Similar: BA Thesis for classification of weasel

Dürr, O., Pauchard, Y., Browarnik, D; Axthelm, R.; Loeser, M. (2015): *Deep Learning on a Raspberry Pi for Real Time Face Recognition*. EG 2015 – Posters 11-12.

Apodemus speciosus

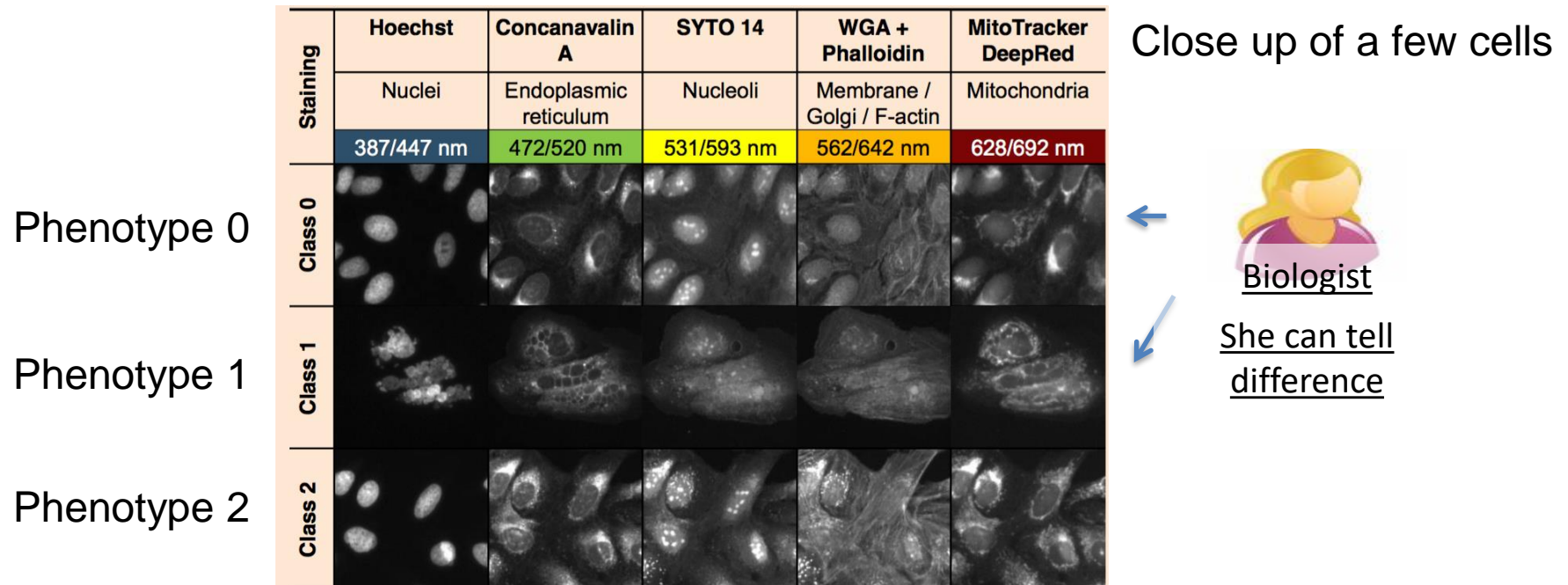


Case Study II

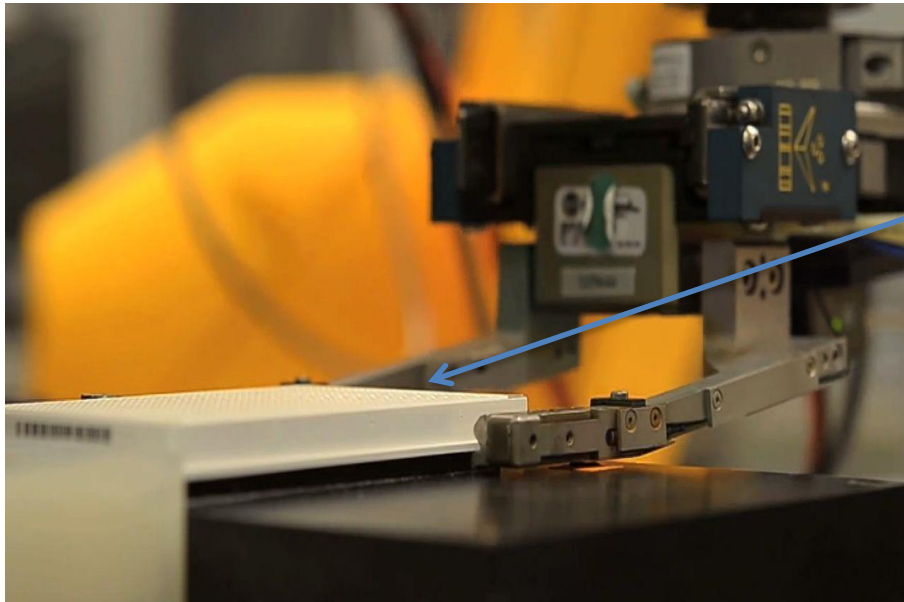
HCS Screening

Phenotypic High Content Screening

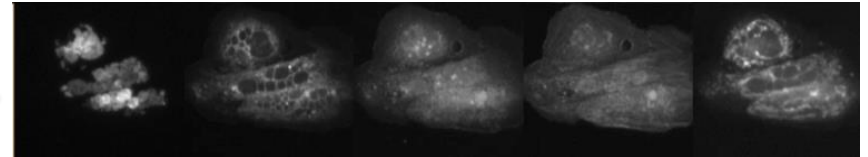
- Compounds (potential drugs) are placed in a well (test-tube)
- Some compounds make cell to react in a particular way (change the phenotype)
- Interest in compounds which change the phenotype in a particular way



Phenotypic High Content Screening: Robotics at Scale



One well (close up)



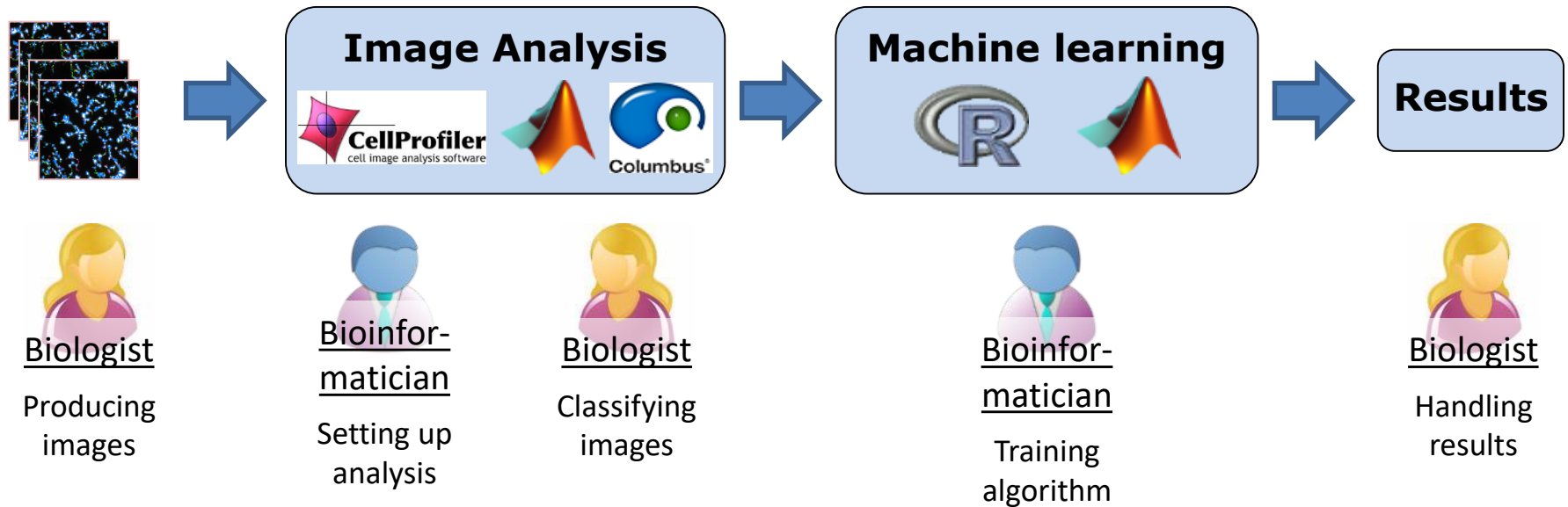
Small screen (by industry standards)

- 20 plates
 - 384 wells
 - 900 cells per well
- ~7 million cells in the screen (350 GB)

➔ need for an automatic approach...

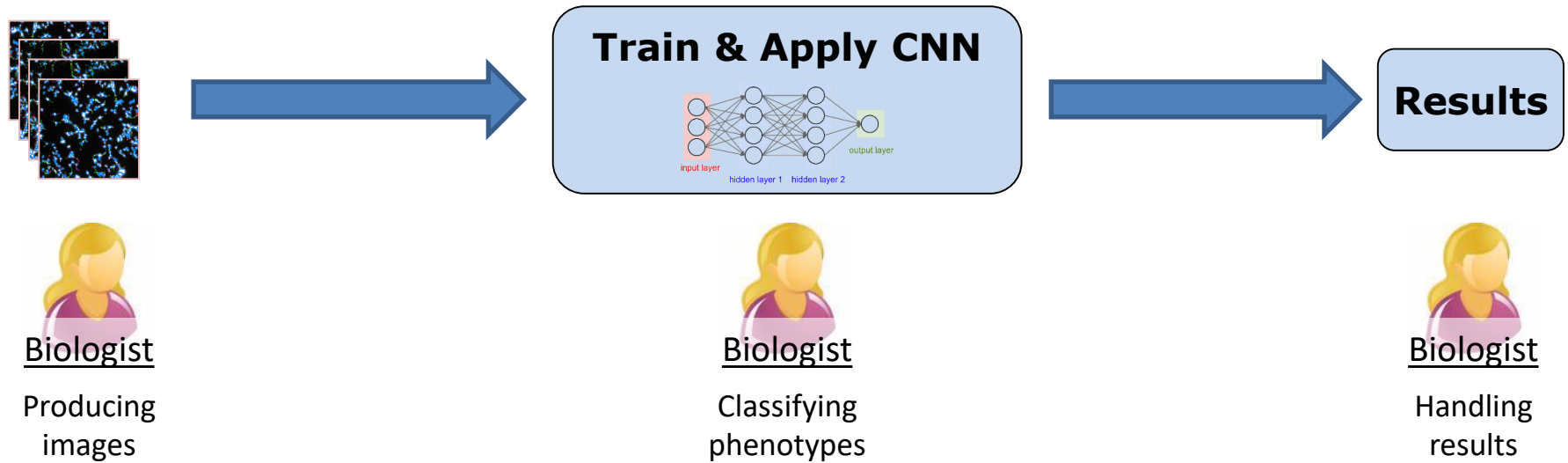
Classical Image Analysis workflow for HCS

Classical HCS workflow



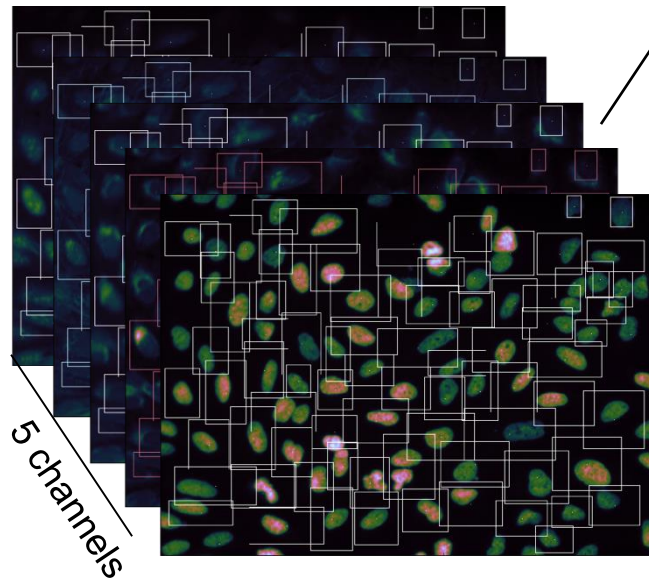
Deep Learning-based workflow of HCS

Deep Learning-based HCS workflow



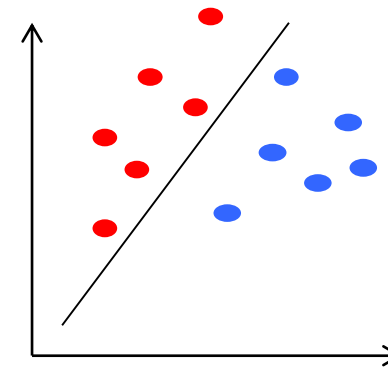
- No time-consuming tuning of image analysis algorithms
- No scripting expertise required
- Single convenient process from start to finish
- Classify training data by simple drag-and-drop
- No tuning of experiment protocols to fit image analysis needs
- Reduction of project times !!

Comparison



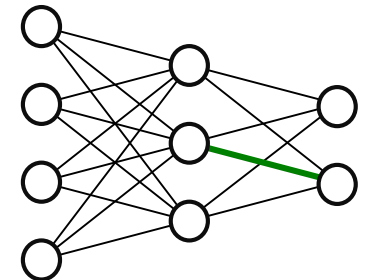
Extracted features (a 396 dimensional vector for a cell)
(1.2, 0.02, ..., 42)

SVM, LDA, RF (baseline)



CNN (new)

Feature extraction using a CNN



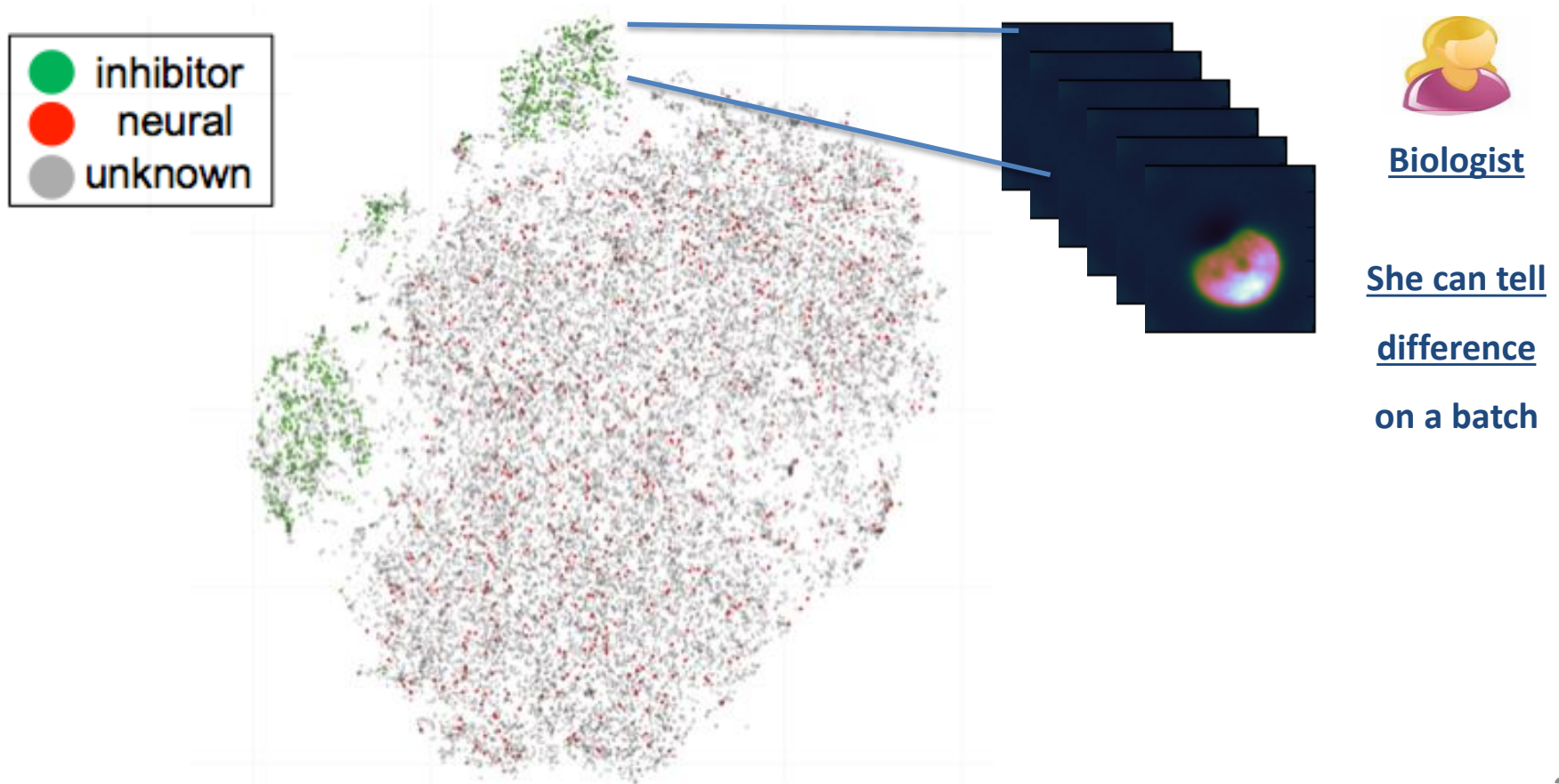
The 5 channels correspond to different stainings.

Cropped cell with 5 channels as input for CNN.

- Current Project with Genedata AG funded by the Swiss Government (CTI, 300+ kCHF)
- Dürr, O., and Sick, B. "Single-cell phenotype classification using deep convolutional neural networks". *Journal of biomolecular screening* 21, 9 (2016), 998-1003

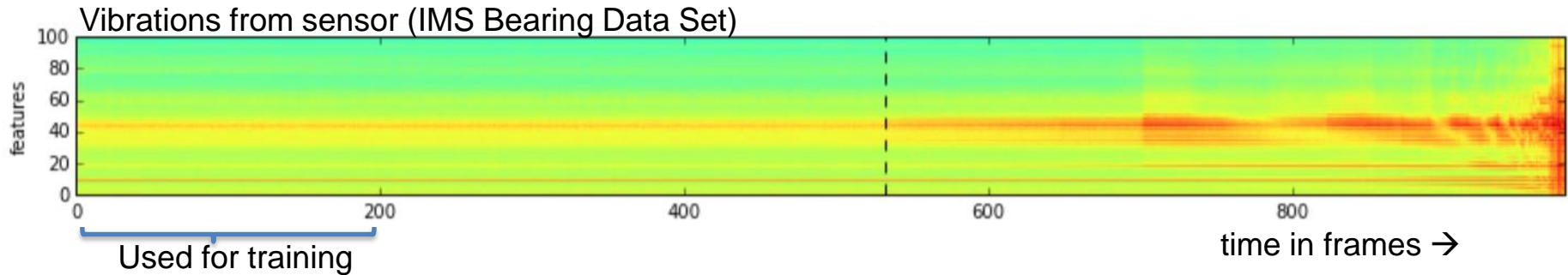
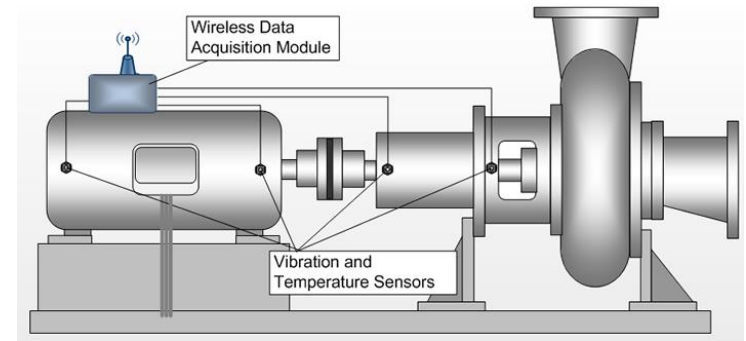
Unsupervised Learning for fast creation of training set

- We can help even more by pre sorting
 - Use a network trained on ImageNet (cats&dogs) VGG16
 - Feed images of cells into network
 - Use intermediate vector (FC7) as input to tSNE

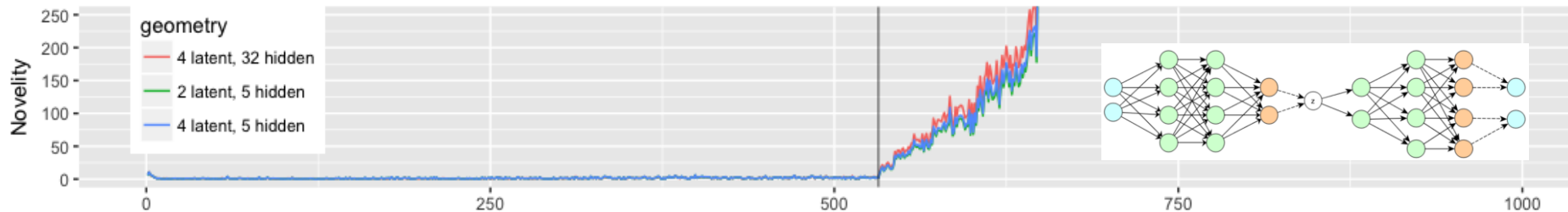


Case Studies III-IV

Condition Monitoring



Deviation from normal condition inferred by a variational auto encoder



- CTI Project Data Driven Condition Monitoring DaCoMo (CTI, 350+ kCHF)
- Stadelmann, T; Tolkachev V; Sick, B; Stampfli, Dürr, O; J. „Beyond ImageNet - Deep Learning in Industrial Practice“ submitted to *Applied Data Science* Braschler, M; Stadelmann, T.; Stockinger, K. (Eds.) Springer

Learning to segment: Vision-based newspaper article segmentation

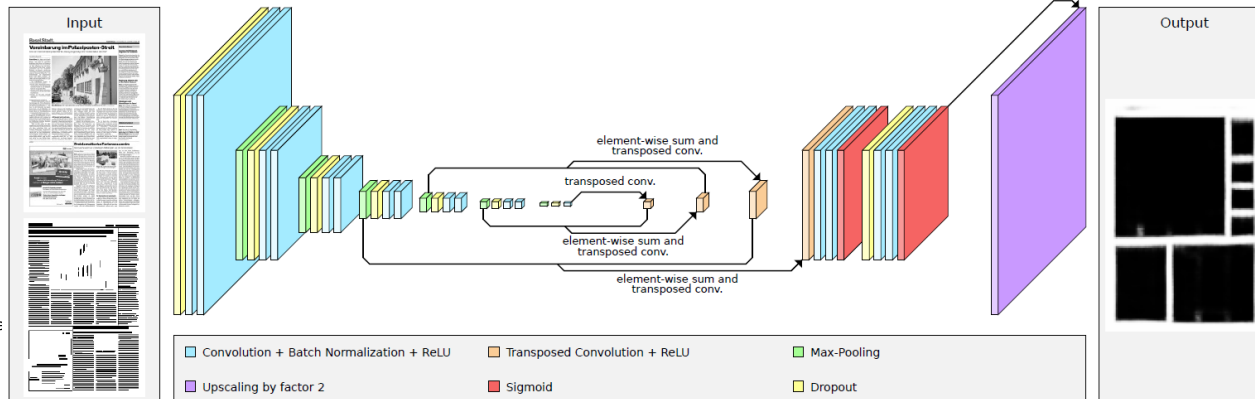
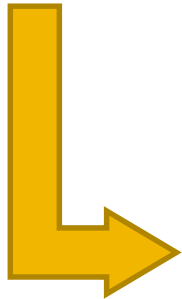
Task:



Results:



Solution:



Introduction → Use Cases → Lessons Learned

3

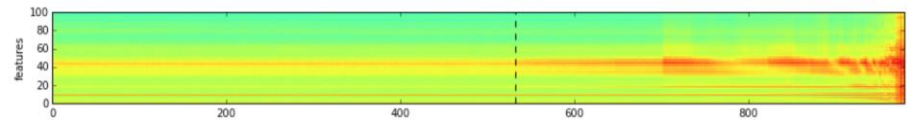
DL using limited resources, and other advice

Beyond ImageNet?

We've successfully trained non-classical DL models to ...

- **Learn to detect novelties / anomalies**

- Task: predictive maintenance
- Approach: autoencoders
- Training data: ca. 400 time points per machine
- Satisfaction: **medium** (worked well for faults humans can recognize; **fails for faults humans don't see coming**)



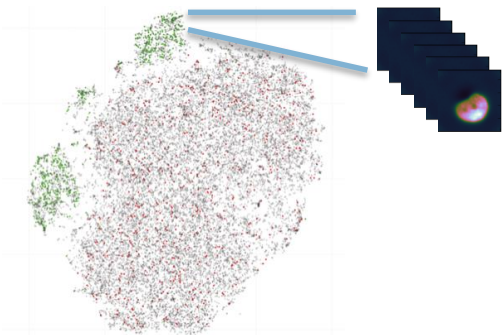
- **Learn to segment**

- Task: segmentation of newspaper pages into articles
- Approach: fully convolutional neural networks
- Training data: ca. 500 fully labeled pages, ca. 5'000 partially labeled pages
- Satisfaction: **high** (much **better than all other automatic approaches**; ca. 70% “felt” accuracy)



- **Learn to use existing networks**

- Task: create labeled data for training
- Approach: use existing network as feature extractor, then cluster
- Satisfaction: **high** (faster human interaction for **creating training data**)



Tips for working with limited data

- **Transfer learning**
 - Use pre-trained networks designed for a “close enough” task (e.g. [VGG-16](#) for image classification)
- **Trainable architectures**
 - Use architectures like [Inception](#) or [ResNet](#) that adapt their complexity to the available data
 - Use network [compression](#) (less parameters → less data needed)
- **Data augmentation**
 - Provide variants of original data that
 - (a) you can create randomly **on the fly**
 - (b) resemble distortions / alterations **relevant and realistic** in practice
- **Unlabeled data**
 - Employ [semi-supervised](#) learning
 - Use high-level features created by a first net to do a [clustering](#) / t-SNE embedding
→ This allows to label lots of data after a short inspection

SMALL DATA (✓)

Important lessons learned

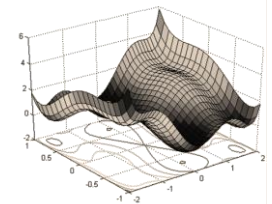
- **A good baseline**

- For a new use case, start from an easy & well understood baseline model (i.e., one closely resembling a published architecture and task)
- **Increase the complexity** of the architecture **slowly**.



- **A suitable loss function**

- Ensure to provide a loss function which **really describes the problem** to be solved
- Especially useful if the task is not classification (e.g., clustering)



- **Debugging**

- **A first DL model** on a completely new task and data set **usually does not work**
- Options:
 - **Hand-calculating** training **equations** for toy examples → bugs e.g. in the loss function?
 - **Visualizing** the pre-processed **data** → bug in data loading?
 - **Visualizing** expected **loss** values → does it learn at all?
 - **Inspecting misclassified** training examples → get intuition into what goes wrong



Conclusions

- **Solid technical foundations** and a **growing base of use cases**
→ the technology is **ready to apply to new areas** (in pattern recognition)
- DL tech **transfer is really fast: ~3 month** from publication to industry
- **Success** (on non-traditional use cases) depends on **experience & experiments**



How to find us

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swiss group for artificial intelligence
and cognitive science



Swiss Alliance for
Data-Intensive Services



APPENDIX

CNN for HCS

Table 1. Architecture of the Convolutional Neural Network.

Layer Description	No. of Images/Feature Maps × Their Dimensions	No. of Weights
Input	5 × 72 × 72	
Convolution (3 × 3)	32 × 70 × 70	32*9*5
Convolution (3 × 3)	32 × 68 × 68	32*9*32
Max pooling (2 × 2)	32 × 34 × 34	
Convolution (3 × 3)	64 × 32 × 32	64*9*32
Convolution (3 × 3)	64 × 30 × 30	64*9*64
Max pooling (2 × 2)	64 × 15 × 15	
Convolution (3 × 3)	128 × 13 × 13	128*9*64
Convolution (3 × 3)	128 × 11 × 11	128*9*128
Max pooling (2 × 2)	128 × 6 × 6	
Fully connected	200	200*128*6*6
Fully connected	200	200*200
Fully connected	50	50*200
Output	4	4*50

Newer Versions use dropout but no batch-norm

More non-traditional DL applications

...beyond image classification

- **Learn to cluster**

- Task: cluster 1s long speech utterances into an unknown number of unknown speakers
- Approach: CNN/RNN to extract embeddings for subsequent hierarchical clustering
- Training data: ca. 20s from 100 speakers
- Satisfaction: **high** (achieved state of the art, doesn't work end-to-end yet)

